2008

Session 6

ARCHIVE 2008

KEY CHALLENGES AND TECHNOLOGY TRENDS IN SOCKET DESIGN

"Automated Topside and Bottomside Testing of POP Packages on a Robotic Handler"

Eric Pensa, Willie Jerrels
Texas Instruments

"High Speed Contactor Interconnect"

David Mahoney
Xilinx, Inc.
Hongjun Yao
Antares Advanced Test Technologies

"Particle Interconnect: Simple and Effective Socket Solution"

Robert Howell
Exatron

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Automated Topside and Bottomside Testing of POP Packages on a Robotic Handler

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Texas Instruments MAKE Test
Handler-Interface Engineering

March 12, 2008

Outline

- Why is topside testing needed
- History of topside testing
- What is topside vs. bottom side testing
- Current status of topside testing
- Future requirements for topside testing

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Why is Topside Testing Needed?

- Customer demand for POP packaging is strong and only expected to grow
- POP packages need to be contacted on both the bottom (BGA) *and* top side (Pads) simultaneously
- Current approach on existing robotic handlers is for bottom side testing only

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Why is topside testing needed?

What is a POP package?

Top POP Memory Package

Top View *Bottom View* *Side view of stacked package*

- POP = Package on Package Technology
- A memory package is stacked directly onto the above POP package
- Customer chooses their own POP Package memory configurations/densities & preferred POP memory vendor (Cont'd)

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Why is topside testing needed?

- Offering a production worthy solution for testing POP packages that is not currently available. Without this test capability the large cost savings achievable with POP packages will not be realized.
- *"Top Test capability is expected to reduce TI costs on selected POP packages considerably. This is a direct result of not having to bring the full memory interface to the bottom BGA, thus decreasing ball count, decreasing substrate complexity, decreasing substrate layer count, and finally decreasing cost."* (Cont'd)

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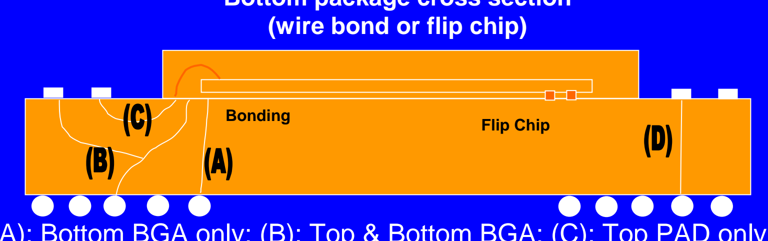
Why is topside testing needed?

Current POP design and test methods require 100% access to the memory device from the bottom BGA solder balls (paths A, B & D below). This practice increases the package pin count, reduces BGA pitch and in turn increases our customer's assembly complexity, adds to system PWB cost and lowers reliability. The goal is to eliminate path B and only have paths A, C & D. (Cont'd)

Bottom package cross section (wire bond or flip chip)



(A): Bottom BGA only; (B): Top & Bottom BGA; (C): Top PAD only

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History of Topside Testing

- First customer request ~ 2.5 years ago for 14x14 POP package
- TI MAKE Test and Delta Contactor teams began development of topside test solution for 14x14 POP package
- Challenge was finding 2 pogopins for bringing signal up to topside
- Unexpected challenge was building non-flat nest PCB board - handler vendor declined!
- Kit and socket were verified Summer 2005 with O/S testing using daisy chains only due to device being cancelled - no production testing ever done w/ 14x14 POP

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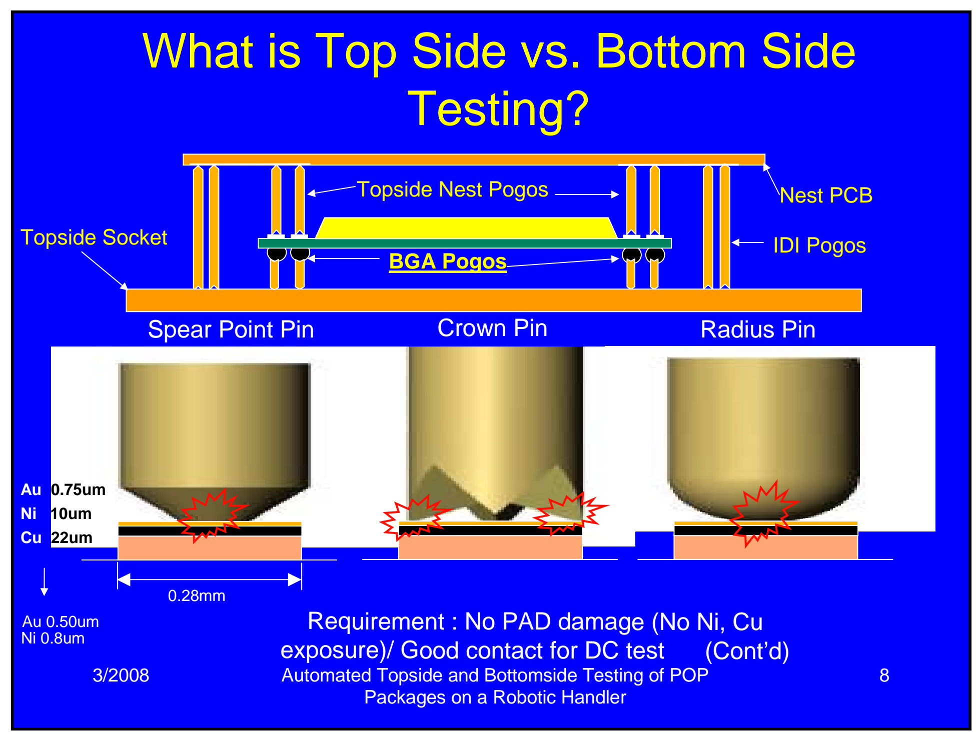
What is Top Side vs. Bottom Side Testing?



Requirement : No PAD damage (No Ni, Cu exposure)/ Good contact for DC test (Cont'd)

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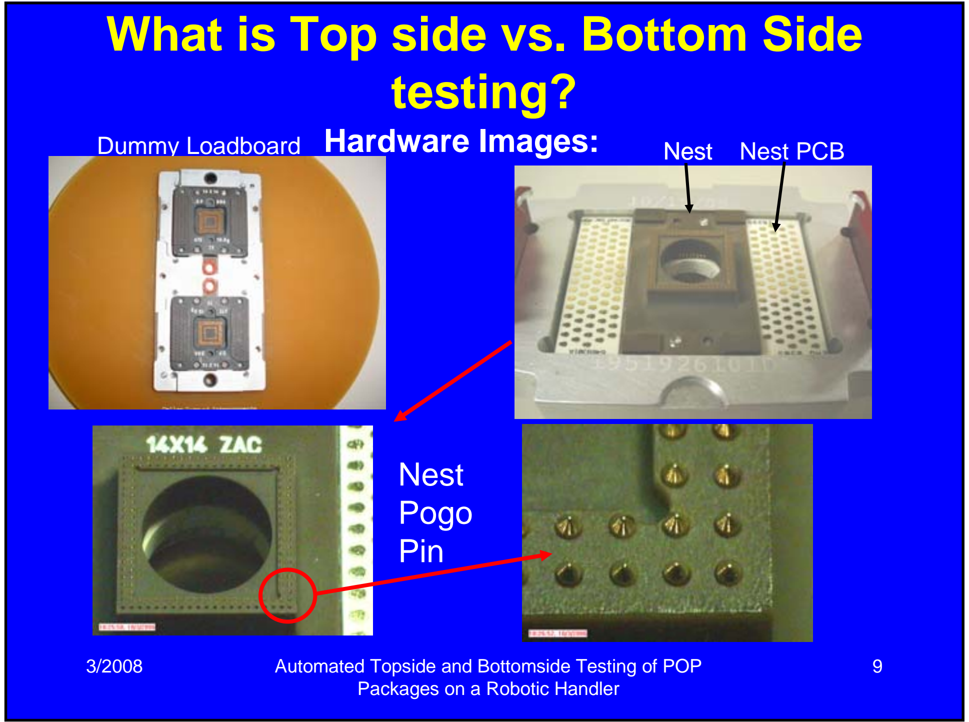

Current Status of Topside Testing

- Topside testing resurrected ~ 1 year ago for a 12x12 POP package by a TI customer
- To meet aggressive 3 month kit/socket request, decision was made to leverage off of 14x14 topside kit as much as possible
- Customer's 2 key requirements: 1) ***NO*** Ni or Cu exposure; 2) "gentle mark" to topside pad will only be accepted
- Topside pogopin from 14x14 kit was single point/spear type: SEM analysis of tested units showed <u>failure to meet both requirements</u>.
- Only 3 "drop-in replacement" pogopins were available for con-sideration: 2 w/ radiused tips & 1 w/ 3 point crown tip

(Cont'd)

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Current Status of Topside Testing

- 14x14 units were run thru the handler with all 3 "drop-in" pogos: SEM testing showed all 3 would meet customer requirements with radiused tip markings being slightly more gentle than 3 point crowns. (Note: No electrical testing; same mechanical settings as used w/ 14x14 kit.)
- Topside Handler Kit, Socket, and O/S Testboards were ordered for the 12x12 POP package
- Both radiused and 3 point crown type pogos were ordered
- Customer preferred the radiused tip (Cont'd)

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- SEM results from **Initial Mechanical Assessment of Probe Pins**:
  - Evaluation varied 1) Probe type 2) Force, 3) # of probe attempts
  - Radial pins exhibited minimal "marking" and no Ni detection
  - Alternate pin styles showed ~2x "mark size" over radial pin

Radial Pin Results – 20g Force:

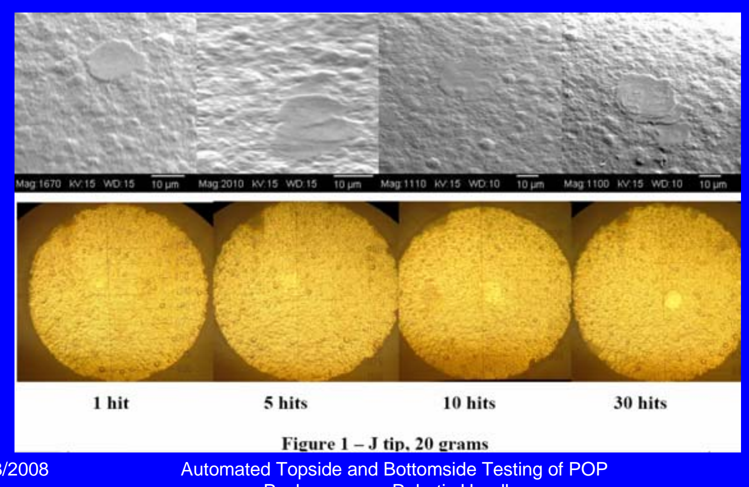

Figure 1 – J tip, 20 grams

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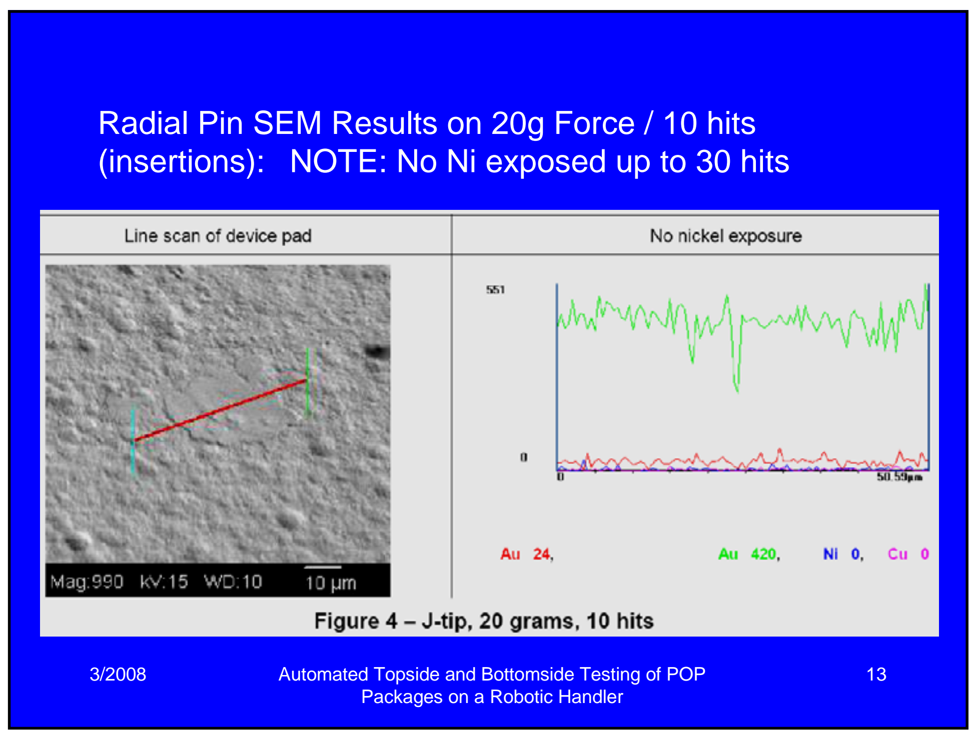
Radial Pin SEM Results on 20g Force / 10 hits (insertions): NOTE: No Ni exposed up to 30 hits
Line scan of device pad
No nickel exposure
Mag:990 kV:15 WD:10 10 µm
Au 24, Au 420, Ni 0, Cu 0
Figure 4 – J-tip, 20 grams, 10 hits
3/2008
Automated Topside and Bottomside Testing of POP Packages on a Robotic Handler
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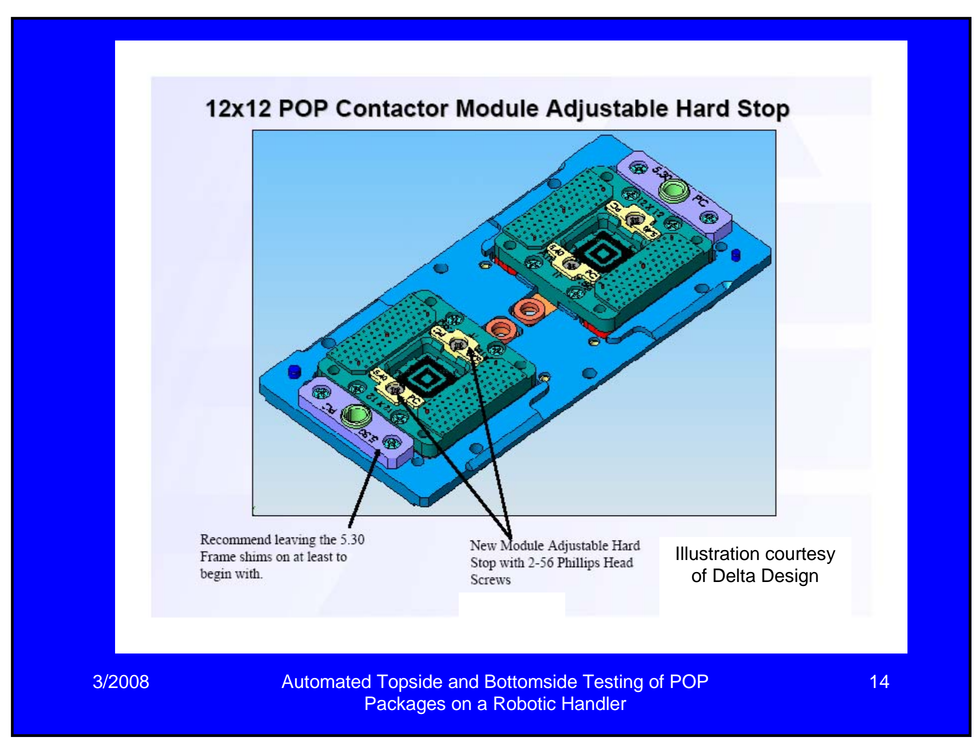
12x12 POP Contactor Module Adjustable Hard Stop
Recommend leaving the 5.30 Frame shims on at least to begin with.
New Module Adjustable Hard Stop with 2-56 Phillips Head Screws
Illustration courtesy of Delta Design
3/2008
Automated Topside and Bottomside Testing of POP Packages on a Robotic Handler
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Current Status of Topside Testing

- To reduce risk, handler vendor was requested to run kit continuity check at all 3 temp's w/ daisy chained 12x12 POP units: good results from both pogo types at all 3 temps!
- Kit arrives in TI Dallas: however live 12x12 POP units proved to be more sensitive than the daisy chained ones: Mis-contact(Bin 8) rates were significantly worse! Fortunately customer received required units throughout troubleshooting phase.
- A multi-month effort began to fine-tune the setup to eliminate mis-contact (Bin 8) with the nest being the focus:

(Cont'd)

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Current Status of Topside Testing

a) "Retainers" were added to the handler nest for pogopin to pad alignment

b) Nest "ceiling" was lowered to counter any package warpage

c) Single ended BGA pogopins replaced w/ double ended as used on 14x14 kit

d) Adding hardstop height with Kapton tape helped; therefore variable hardstops on the contactor were offered [5.30 thru 5.45mm in .05 steps] to deal with package thickness variances

e) Variable hardstops also added to the contactor modules to replicate the success of hand test lids *w/ hardstops closer to the POP unit under test* by reducing package flexing possibility – finally both chucks for the 1st time recorded 0% Bin 8 for 1st pass test!

f) Same chuck/nest assemblies were transferred to TI Asia; 0% Bin 8 was achieved with same units tested in Dallas

(Cont'd)

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Future Requirements of Topside Testing

Where are we/what have we learned:

- Performing *both* top *and* bottomside testing is a "very fine balancing act"
- Nest issues contributed to miscontact in the following ways:
  a) new nest material was needed to avoid expansion due to moisture
  b) nest pogopin tip shape, size & XY movement required much attention
  c) nest pocket design & QC process required enhancements over existing approaches that have served bottomside nests well for years
- POP package issues contributed to miscontact in the following ways:
  a) using daisy chained devices were not as helpful in kit design for topside test
  b) package warpage caused offsets to topside pads
  c) sawing process was changed to reduce offsets to topside pads
  d) dimensions and warpage need to be better controlled than for packages only needing bottomside test; topside nests are less tolerant of package variations than typical nests **(Cont'd)**

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Future Requirements of Topside Testing

- Will new nest designs be needed for thinner POP packages that are more prone to warpage?
- Topside nests and hand test lid assemblies are very expensive with long lead times; they need to have maximum flexibility to accommodate package thickness differences
- Will new nest designs be needed for POP packages with bare die on topside?
- Current testing is for single site; what challenges will multi-site testing present?

(Cont'd)

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Future Requirements of Topside

- Having our strategic socket vendors producing turnkey topside sockets and hand test lids [nest PCB and new pogo designs will be needed]
- Developing topside testing solutions for other strategic handlers
- Current topside pogopins are very expensive with lead times up to 6 to 8 weeks; both need to be reduced

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High Speed Contactor Interconnect

2008 Burn-in and Test Socket Workshop
March 9 - 12, 2008

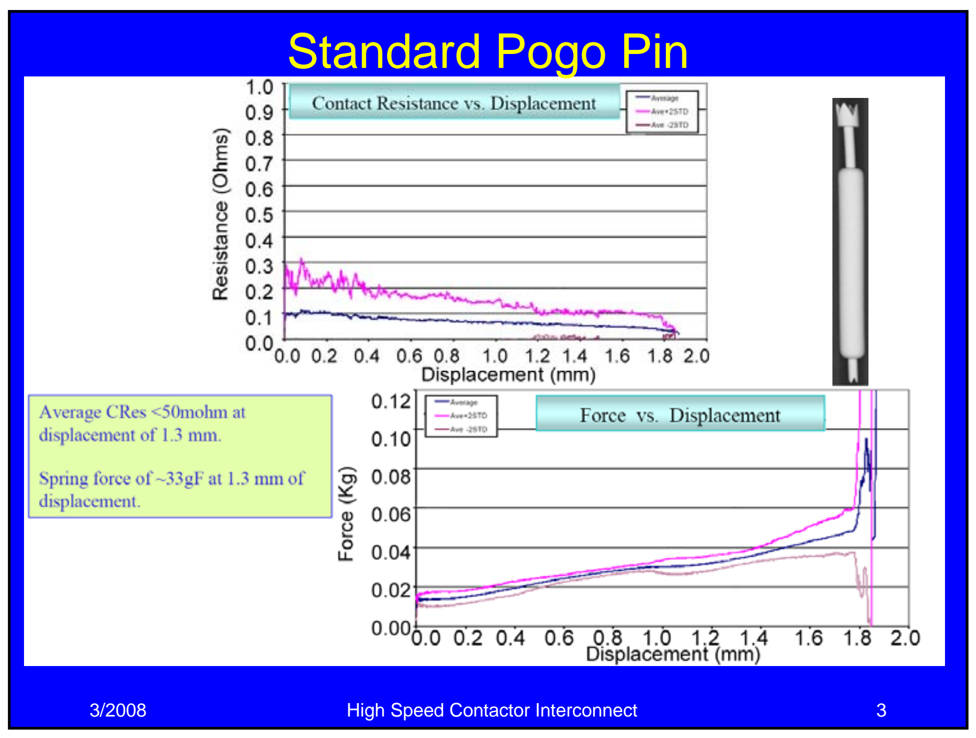
David Mahoney
Xilinx, Inc.
Sr. Product Engineer

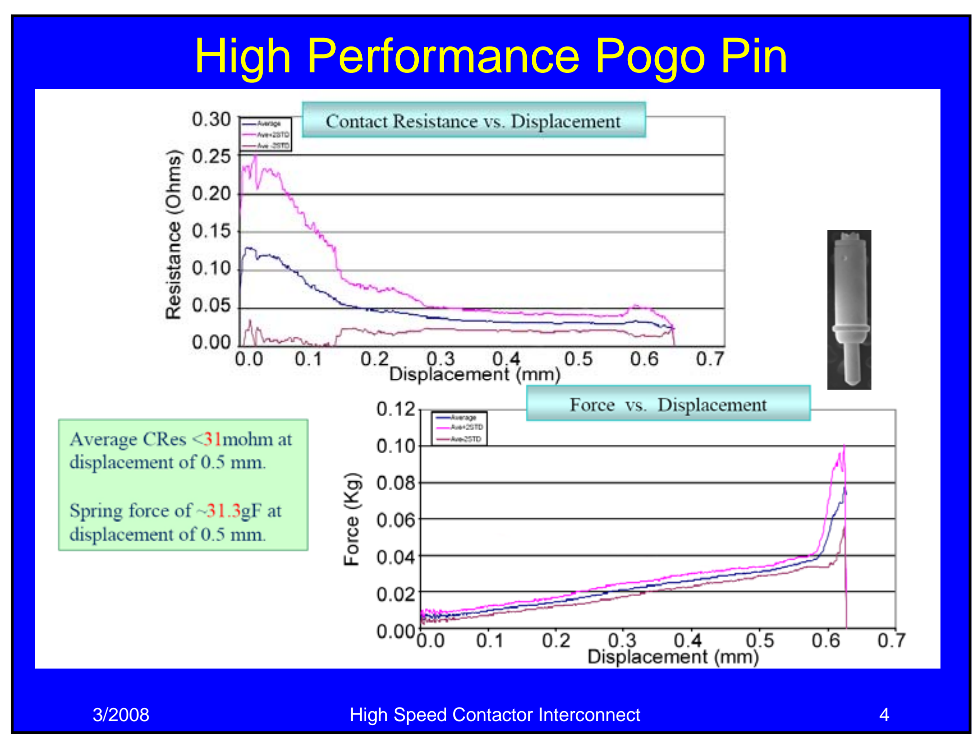
Hongjun Yao
Antares Advanced Test Technology
Signal Integrity Manager

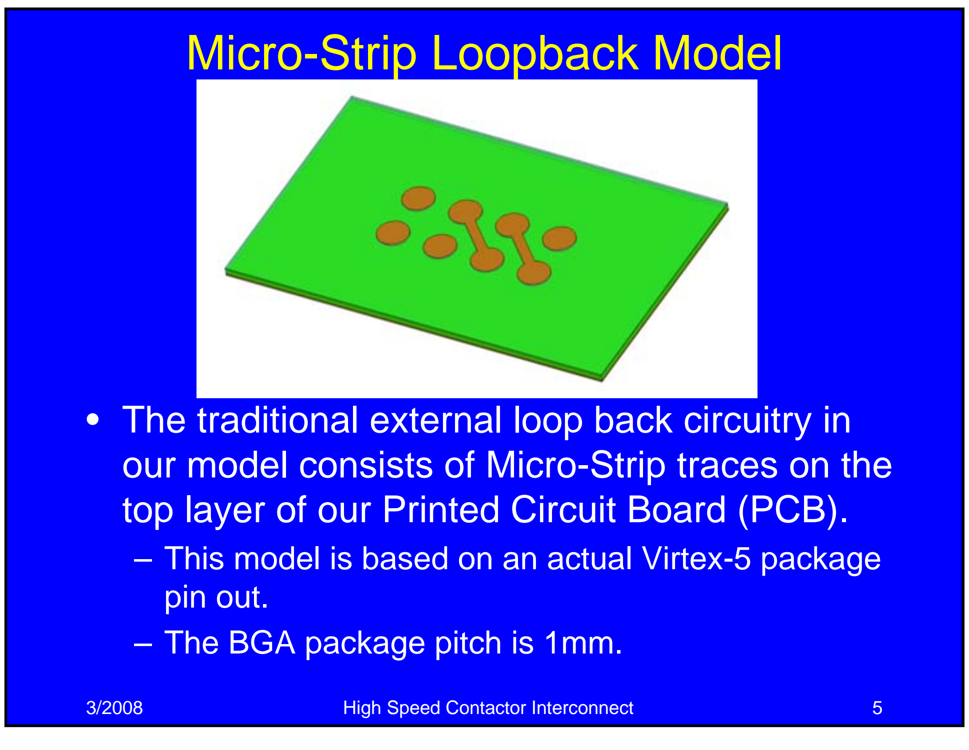
High Speed Contactor Interconnect Background

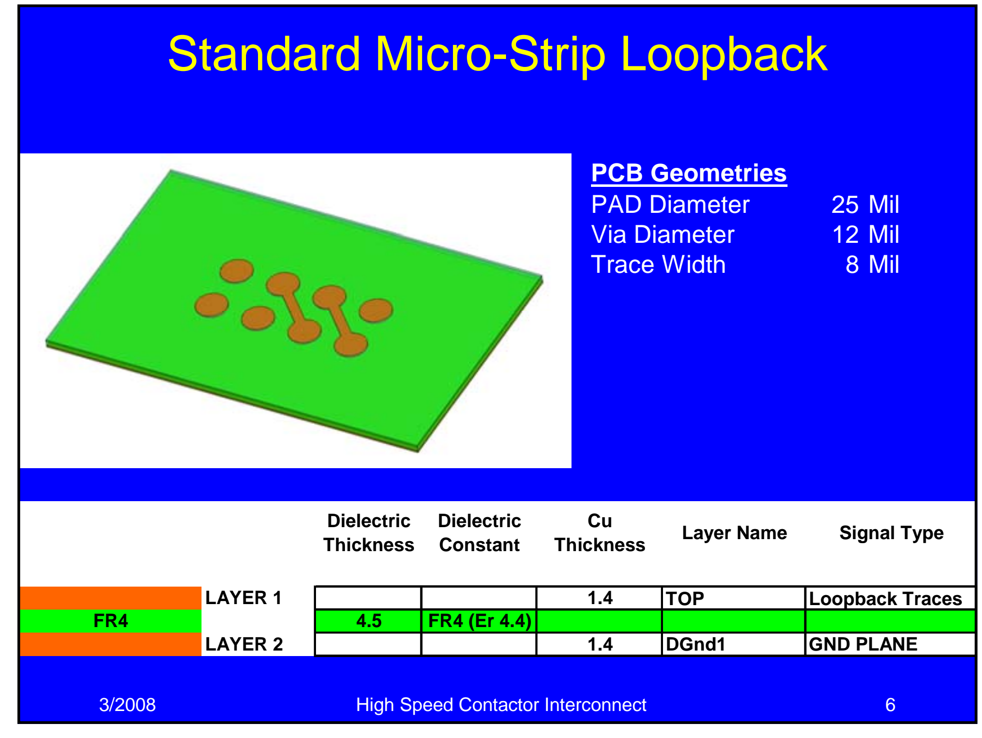
- Traditional external loop back circuitry consists of two contact elements in a socket and a loop back trace on the Printed Circuit Board (PCB).
- As the length of Pogo Pins are reduced the contact force and the overall travel of the Pogo Pin are also reduced.
- This paper looks at the performance of using long electrical contacts in conjunction with a interconnect that is placed inside the socket body of a traditional Automated Test Socket for a BGA package.
- We have also compared the electrical performance to a High Performance Contactor using the standard loop back trace on the PCB.

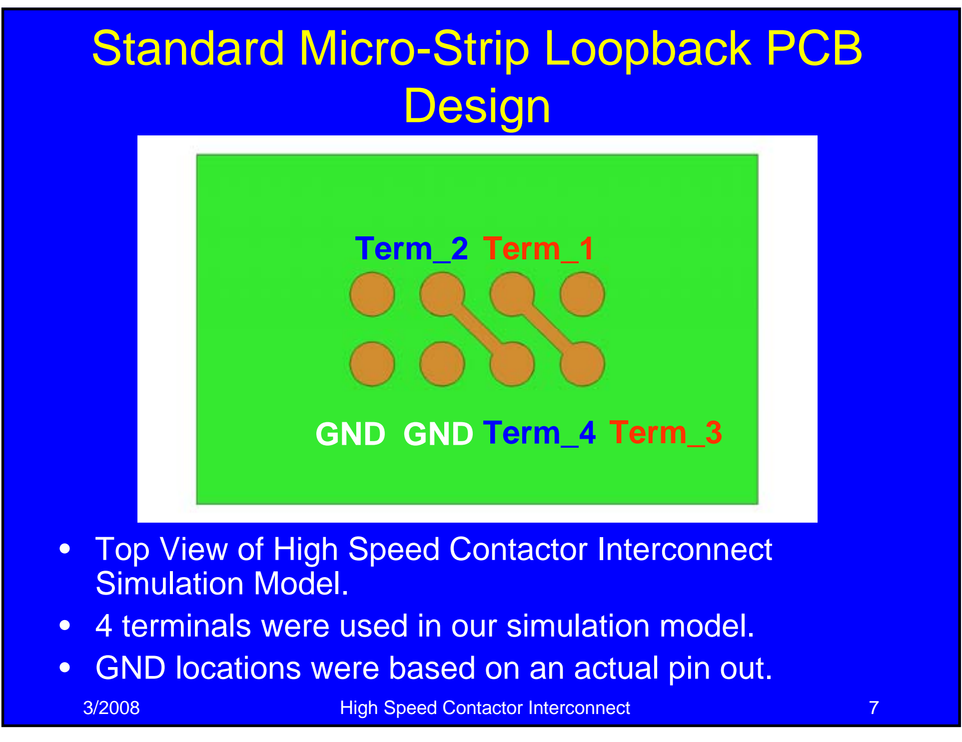
3/2008 High Speed Contactor Interconnect 2

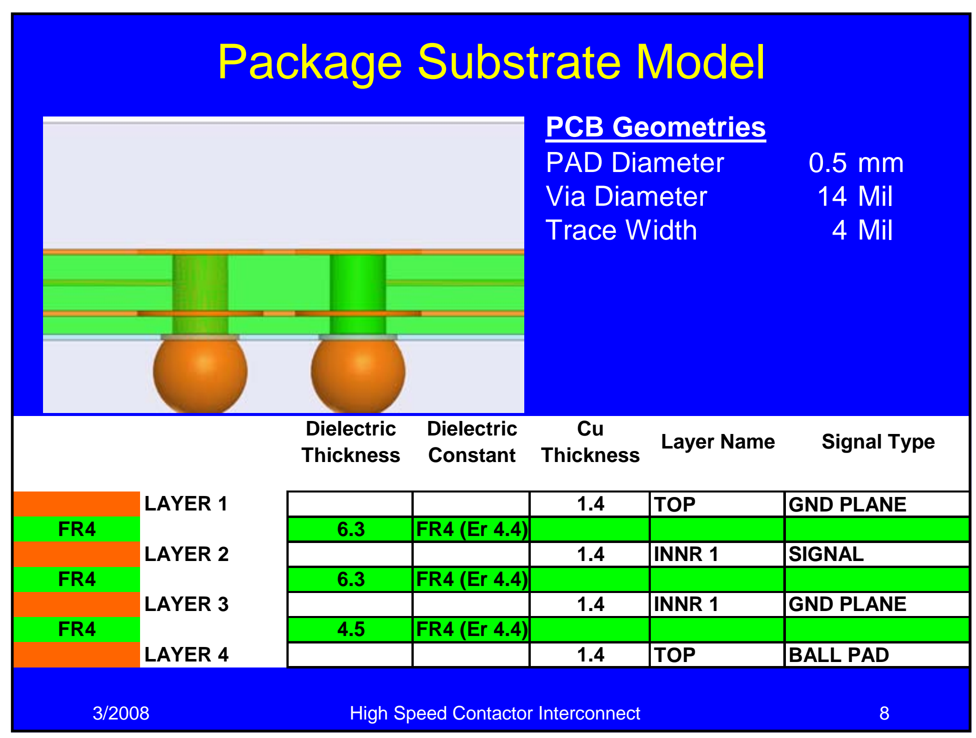

Standard Pogo Pin
Contact Resistance vs. Displacement
Resistance (Ohms)
Displacement (mm)
Average CRes <50mohm at displacement of 1.3 mm.
Spring force of ~33gF at 1.3 mm of displacement.
Force vs. Displacement
Force (Kg)
Displacement (mm)
3/2008
High Speed Contactor Interconnect
3


High Performance Pogo Pin
Contact Resistance vs. Displacement
Resistance (Ohms)
Displacement (mm)
Average CRes <31mohm at displacement of 0.5 mm.
Spring force of ~31.3gF at displacement of 0.5 mm.
Force vs. Displacement
Force (Kg)
Displacement (mm)
3/2008
High Speed Contactor Interconnect
4


Micro-Strip Loopback Model
• The traditional external loop back circuitry in our model consists of Micro-Strip traces on the top layer of our Printed Circuit Board (PCB).
– This model is based on an actual Virtex-5 package pin out.
– The BGA package pitch is 1mm.
3/2008
High Speed Contactor Interconnect
5

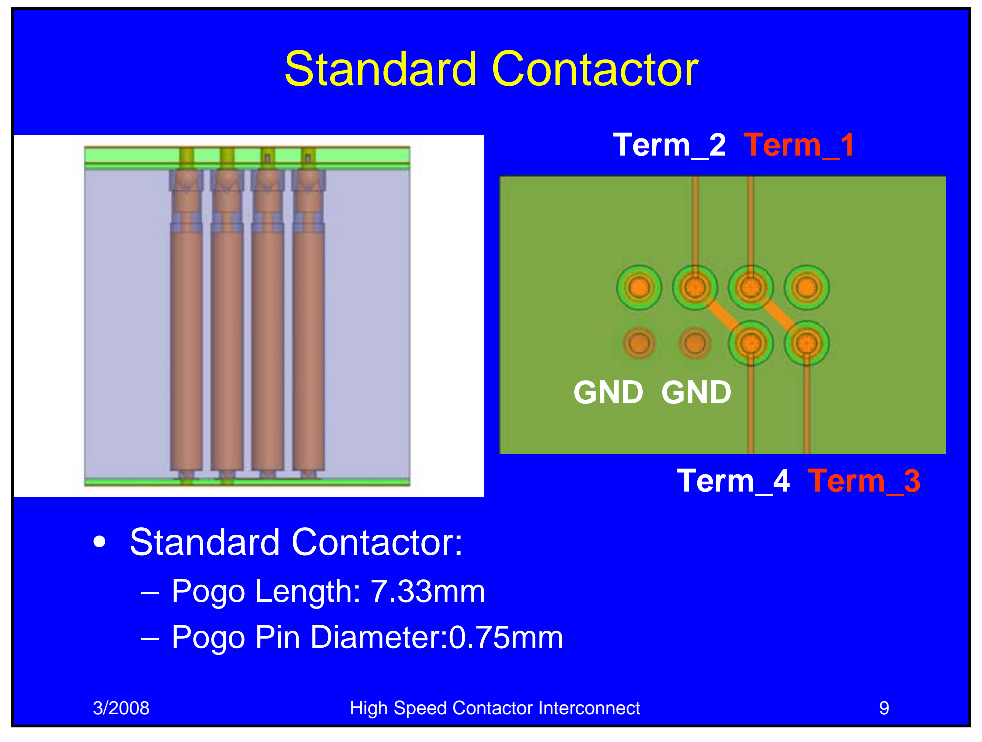

Standard Micro-Strip Loopback
PCB Geometries
PAD Diameter 25 Mil
Via Diameter 12 Mil
Trace Width 8 Mil
Dielectric Thickness
Dielectric Constant
Cu Thickness
Layer Name
Signal Type
LAYER 1
1.4
TOP
Loopback Traces
FR4
4.5
FR4 (Er 4.4)
LAYER 2
1.4
DGnd1
GND PLANE
3/2008
High Speed Contactor Interconnect
6





		Dielectric Thickness	Dielectric Constant	Cu Thickness	Layer Name	Signal Type
	LAYER 1			1.4	TOP	GND PLANE
FR4		6.3	FR4 (Er 4.4)			
	LAYER 2			1.4	INNR 1	SIGNAL
FR4		6.3	FR4 (Er 4.4)			
	LAYER 3			1.4	INNR 1	GND PLANE
FR4		4.5	FR4 (Er 4.4)			
	LAYER 4			1.4	TOP	BALL PAD

Paper #2


Standard Contactor
Term_2 Term_1
GND GND
Term_4 Term_3
• Standard Contactor:
– Pogo Length: 7.33mm
– Pogo Pin Diameter:0.75mm
3/2008
High Speed Contactor Interconnect
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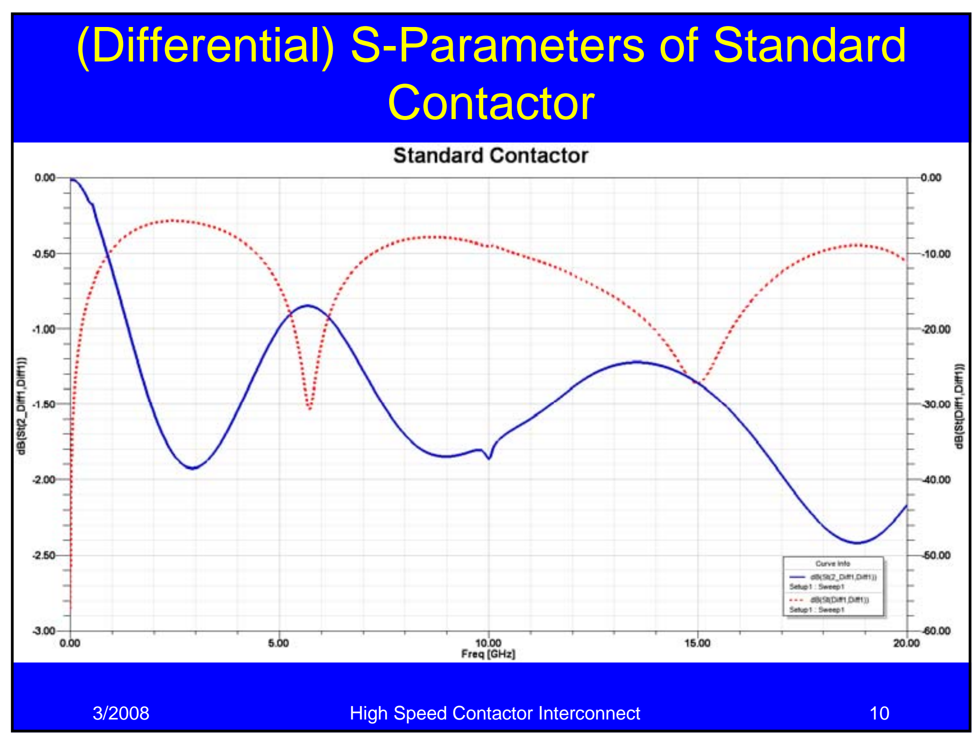
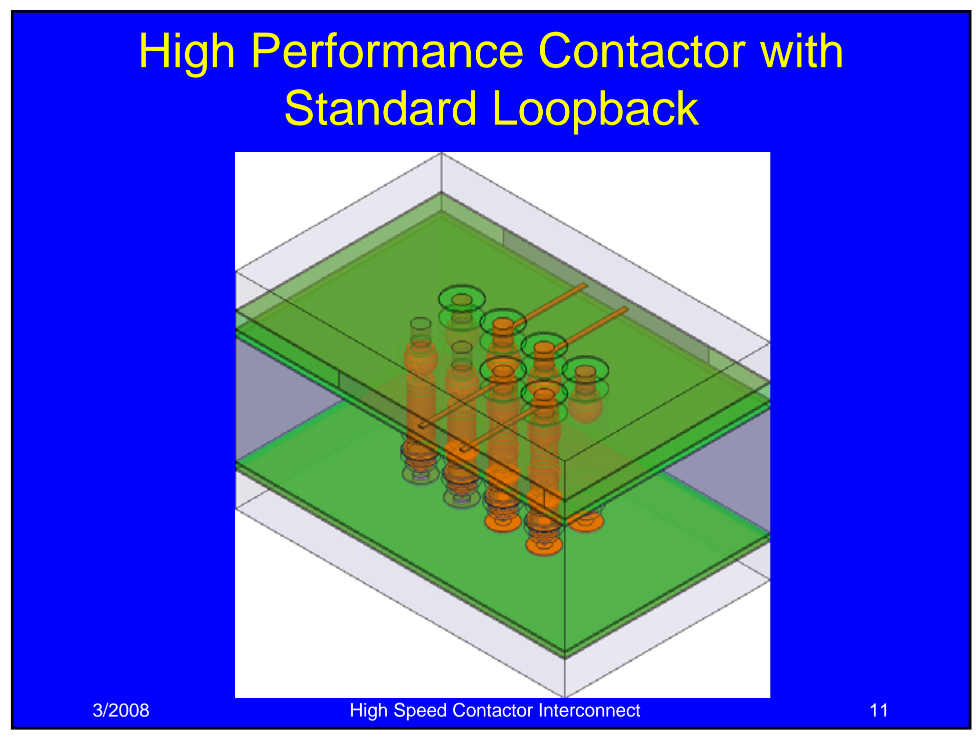

(Differential) S-Parameters of Standard Contactor
Standard Contactor
Freq [GHz]
3/2008
High Speed Contactor Interconnect
10


High Performance Contactor with
Standard Loopback
3/2008
High Speed Contactor Interconnect
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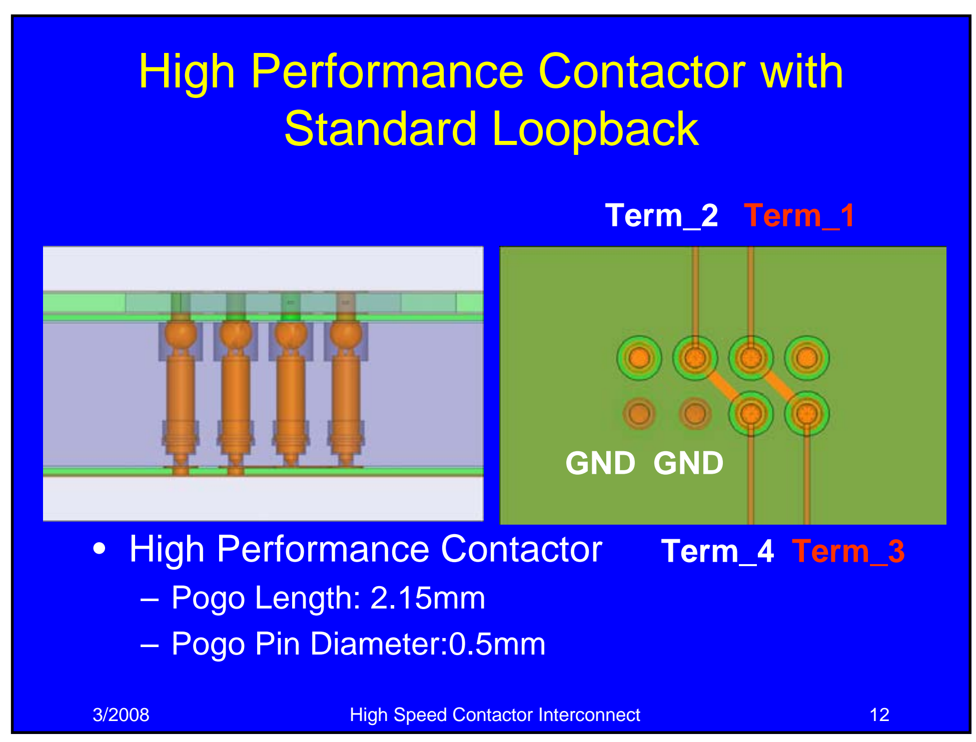
High Performance Contactor with
Standard Loopback
Term_2
Term_1
GND
GND
Term_4
Term_3
• High Performance Contactor
– Pogo Length: 2.15mm
– Pogo Pin Diameter:0.5mm
3/2008
High Speed Contactor Interconnect
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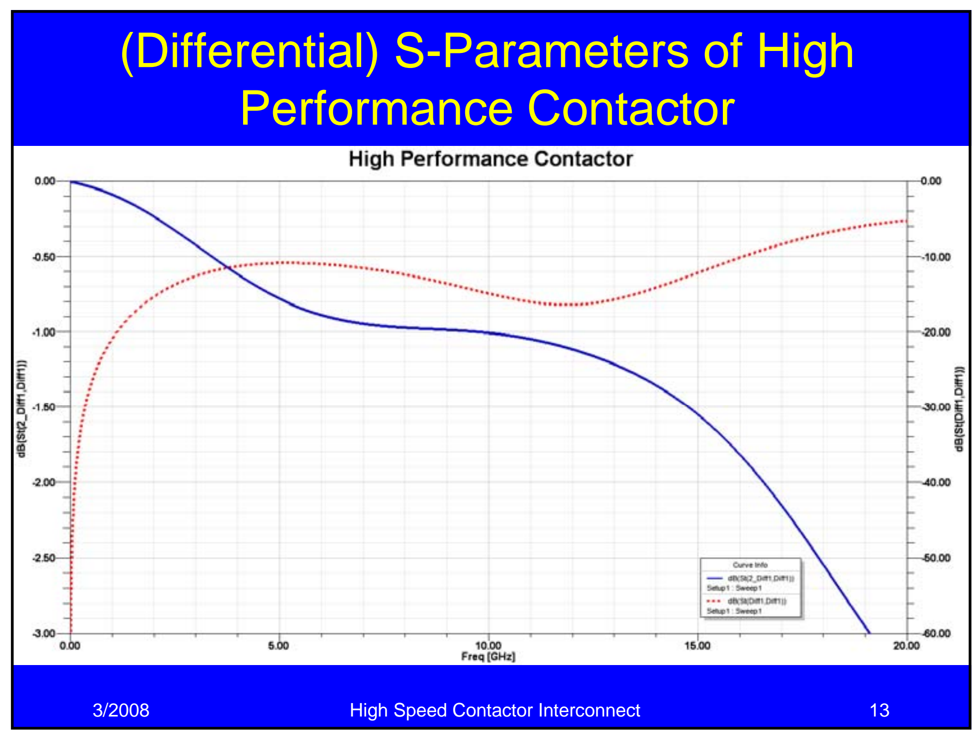
(Differential) S-Parameters of High Performance Contactor
High Performance Contactor
Freq [GHz]
dB(St(2_Diff1,Diff1))
dB(St(Diff1,Diff1))
Curve Info
3/2008
High Speed Contactor Interconnect
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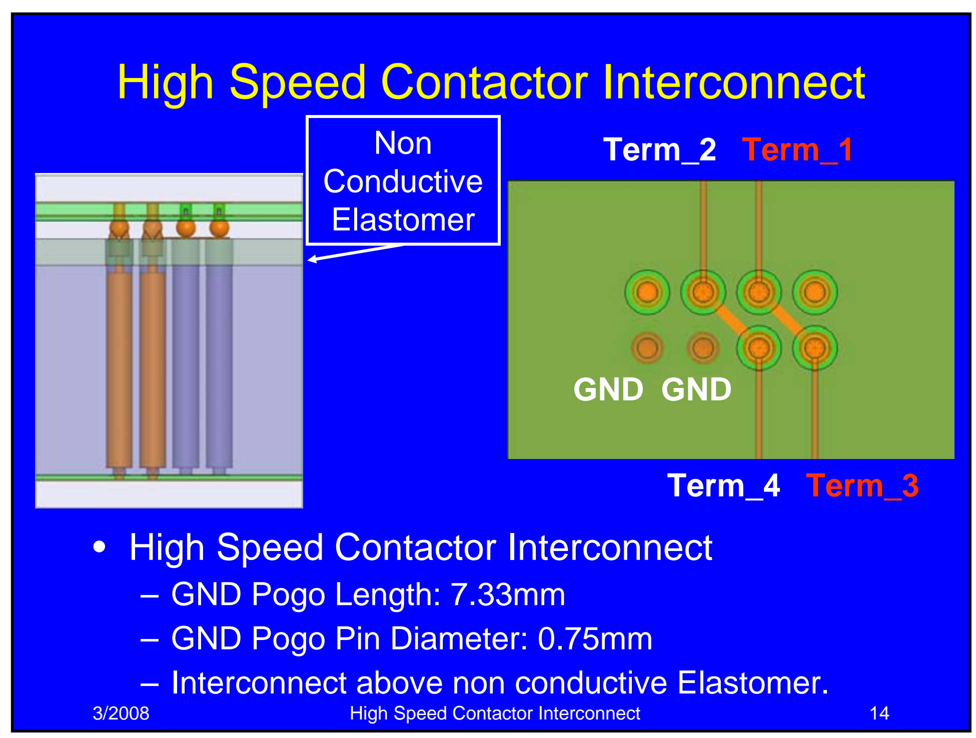
High Speed Contactor Interconnect
Non Conductive Elastomer
Term_2
Term_1
GND
GND
Term_4
Term_3
• High Speed Contactor Interconnect
– GND Pogo Length: 7.33mm
– GND Pogo Pin Diameter: 0.75mm
– Interconnect above non conductive Elastomer.
3/2008
High Speed Contactor Interconnect
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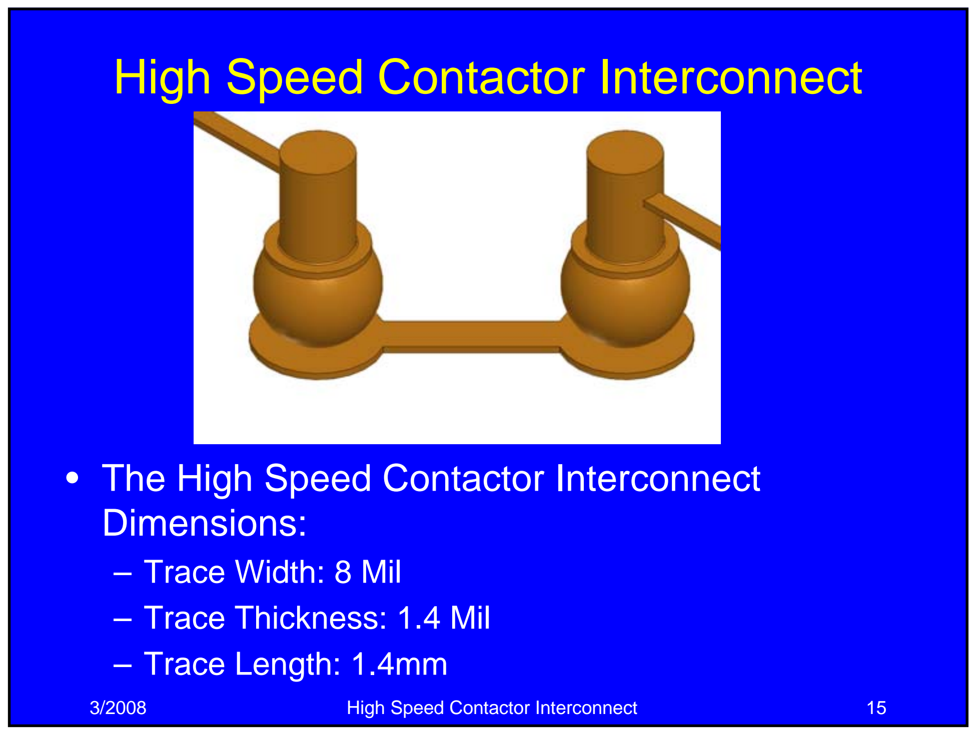
High Speed Contactor Interconnect
• The High Speed Contactor Interconnect Dimensions:
– Trace Width: 8 Mil
– Trace Thickness: 1.4 Mil
– Trace Length: 1.4mm
3/2008
High Speed Contactor Interconnect
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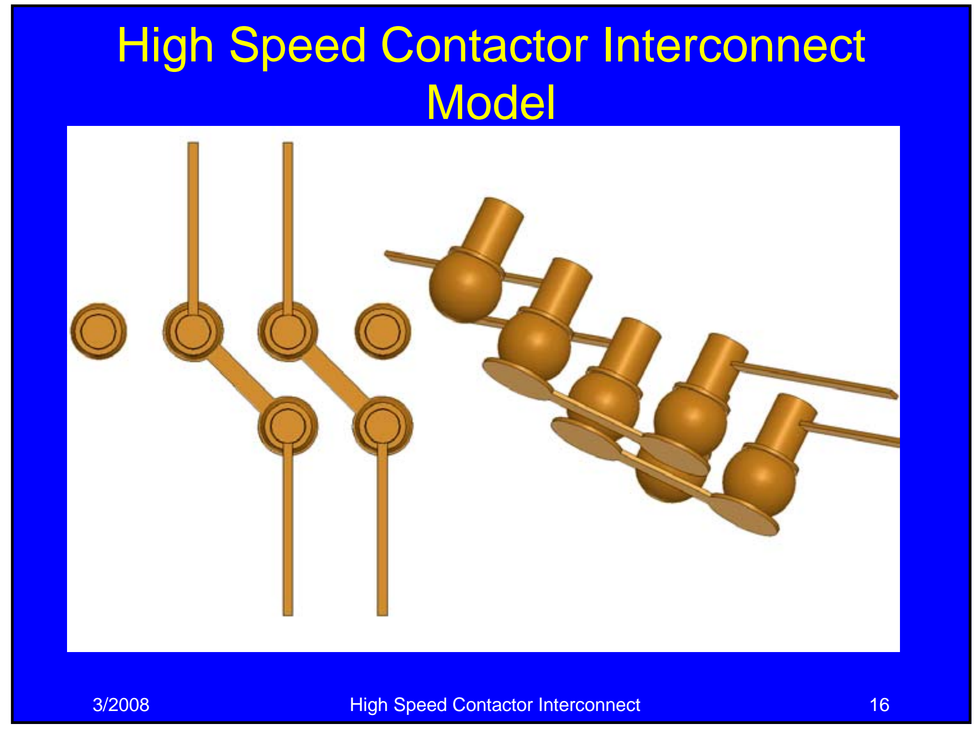
High Speed Contactor Interconnect Model
3/2008
High Speed Contactor Interconnect
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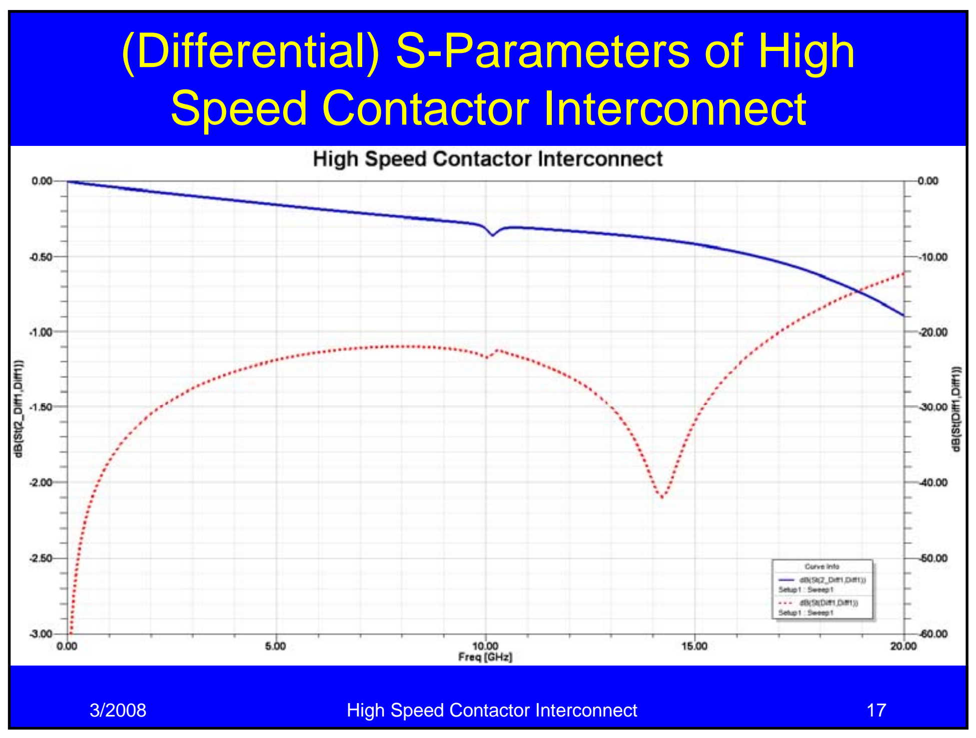
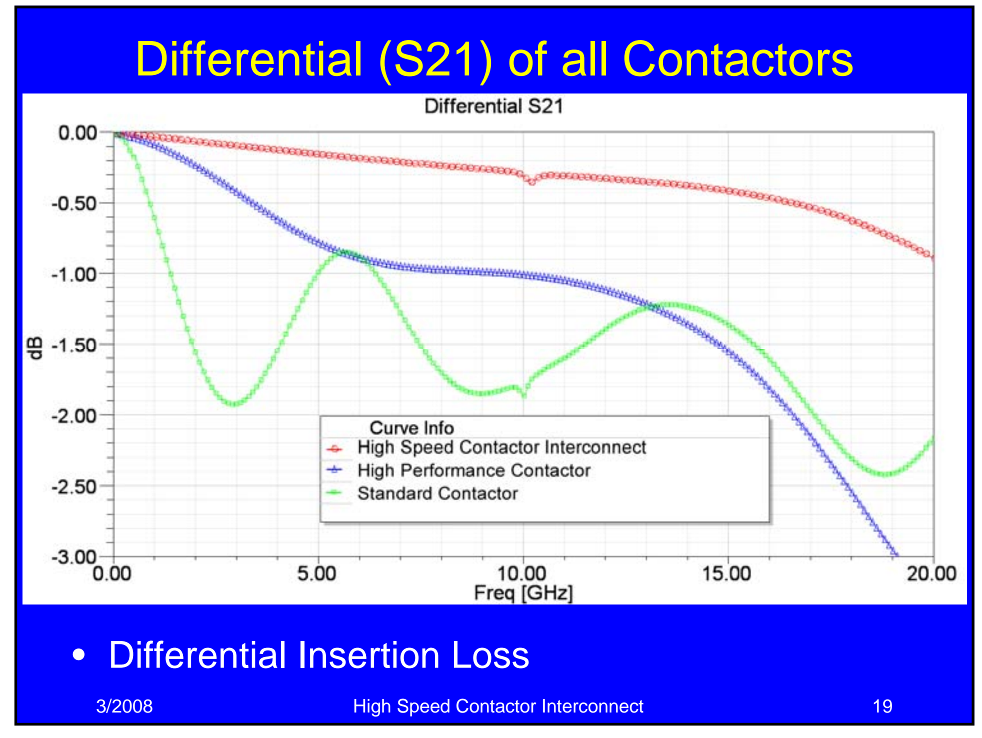


Contactor Comparisons

- Differential Insertion Loss
- Differential Return Loss
- Differential TDR

3/2008 High Speed Contactor Interconnect 18


Differential (S21) of all Contactors
Differential S21
0.00
-0.50
-1.00
-1.50
-2.00
-2.50
-3.00
dB
0.00
5.00
10.00
15.00
20.00
Freq [GHz]
Curve Info
High Speed Contactor Interconnect
High Performance Contactor
Standard Contactor
• Differential Insertion Loss
3/2008
High Speed Contactor Interconnect
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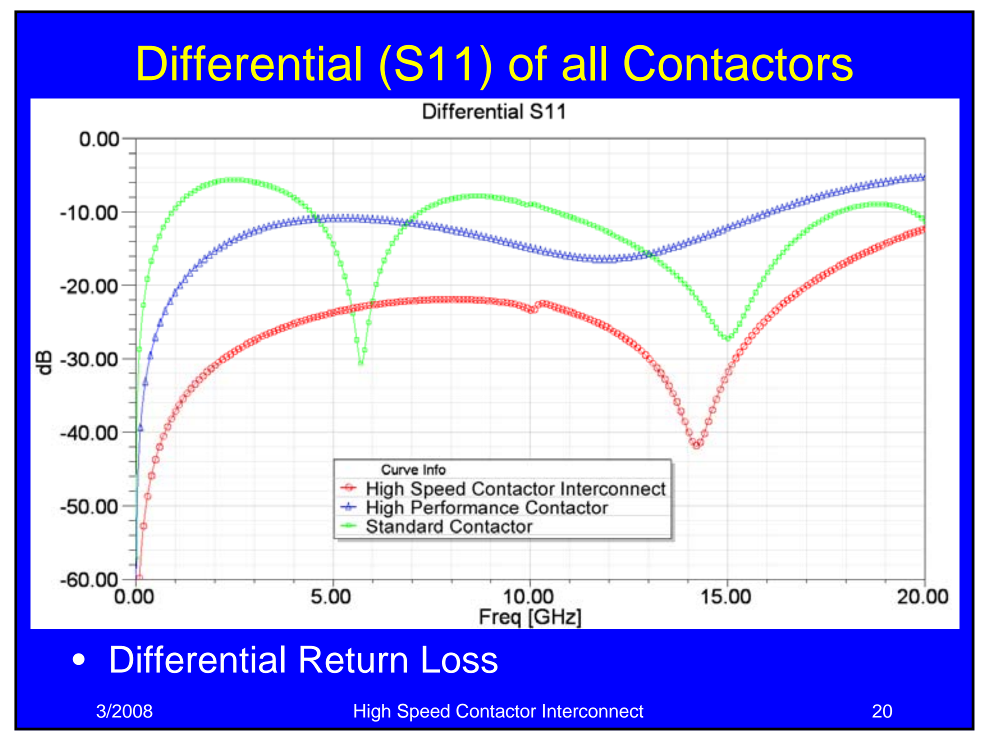
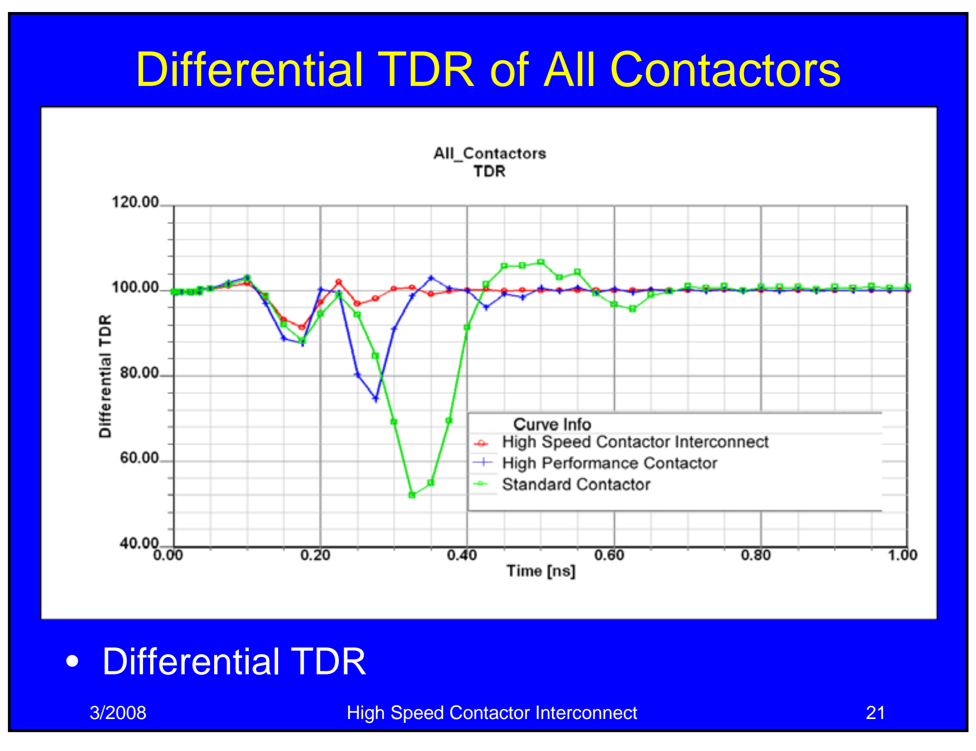

Differential (S11) of all Contactors
Differential S11
0.00
-10.00
-20.00
-30.00
-40.00
-50.00
-60.00
dB
0.00
5.00
10.00
15.00
20.00
Freq [GHz]
Curve Info
High Speed Contactor Interconnect
High Performance Contactor
Standard Contactor
• Differential Return Loss
3/2008
High Speed Contactor Interconnect
20


Differential TDR of All Contactors
All_Contactors
TDR
120.00
100.00
80.00
60.00
40.00
Differential TDR
0.00
0.20
0.40
0.60
0.80
1.00
Time [ns]
Curve Info
High Speed Contactor Interconnect
High Performance Contactor
Standard Contactor
• Differential TDR
3/2008
High Speed Contactor Interconnect
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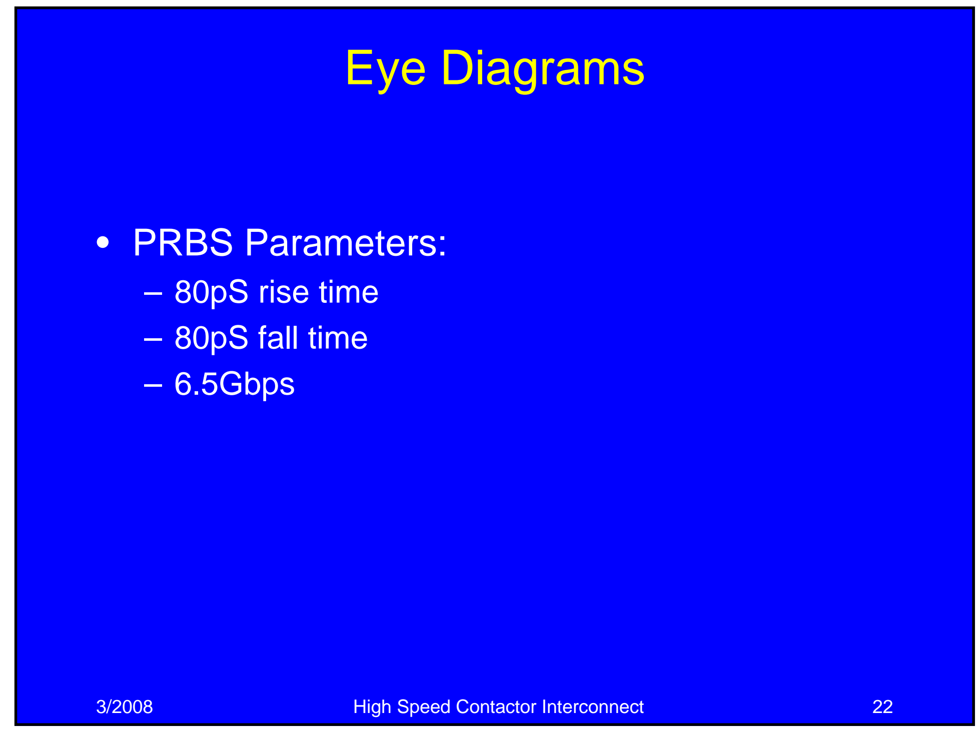
Eye Diagrams
• PRBS Parameters:
– 80pS rise time
– 80pS fall time
– 6.5Gbps
3/2008
High Speed Contactor Interconnect
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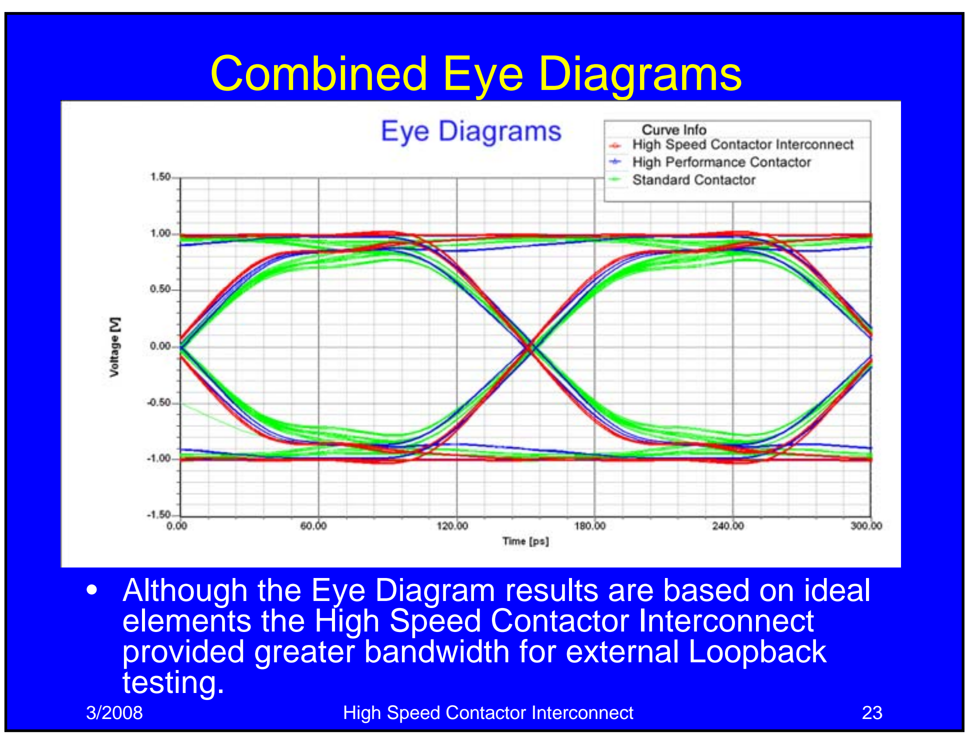

Combined Eye Diagrams
Eye Diagrams
Curve Info
High Speed Contactor Interconnect
High Performance Contactor
Standard Contactor
Voltage [V]
1.50
1.00
0.50
0.00
-0.50
-1.00
-1.50
0.00
60.00
120.00
180.00
240.00
300.00
Time [ps]
• Although the Eye Diagram results are based on ideal elements the High Speed Contactor Interconnect provided greater bandwidth for external Loopback testing.
3/2008
High Speed Contactor Interconnect
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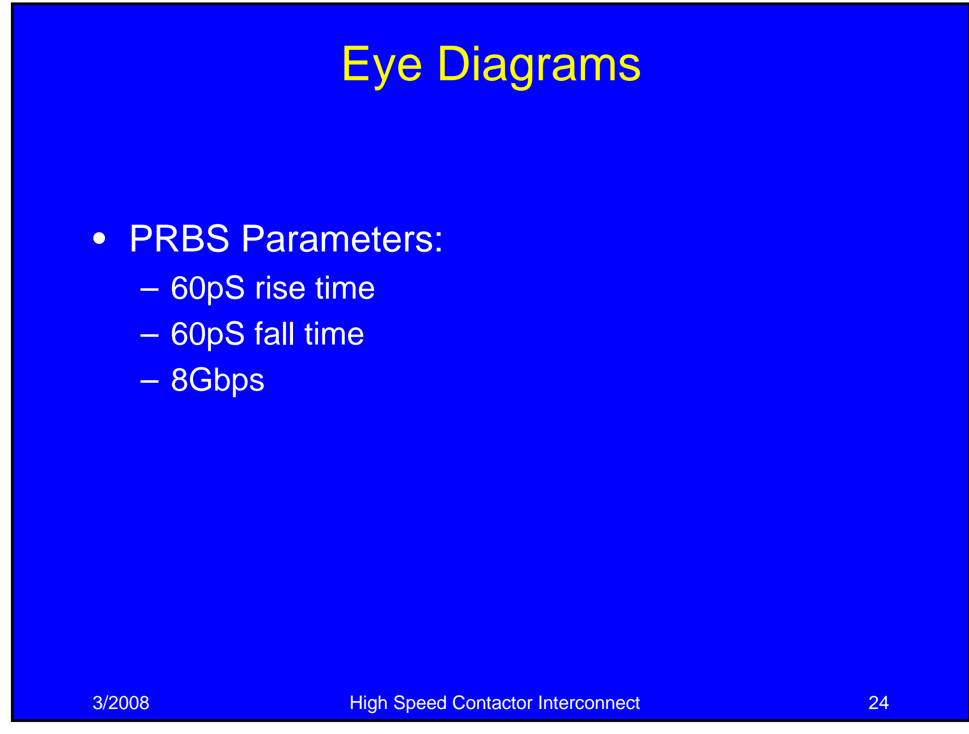
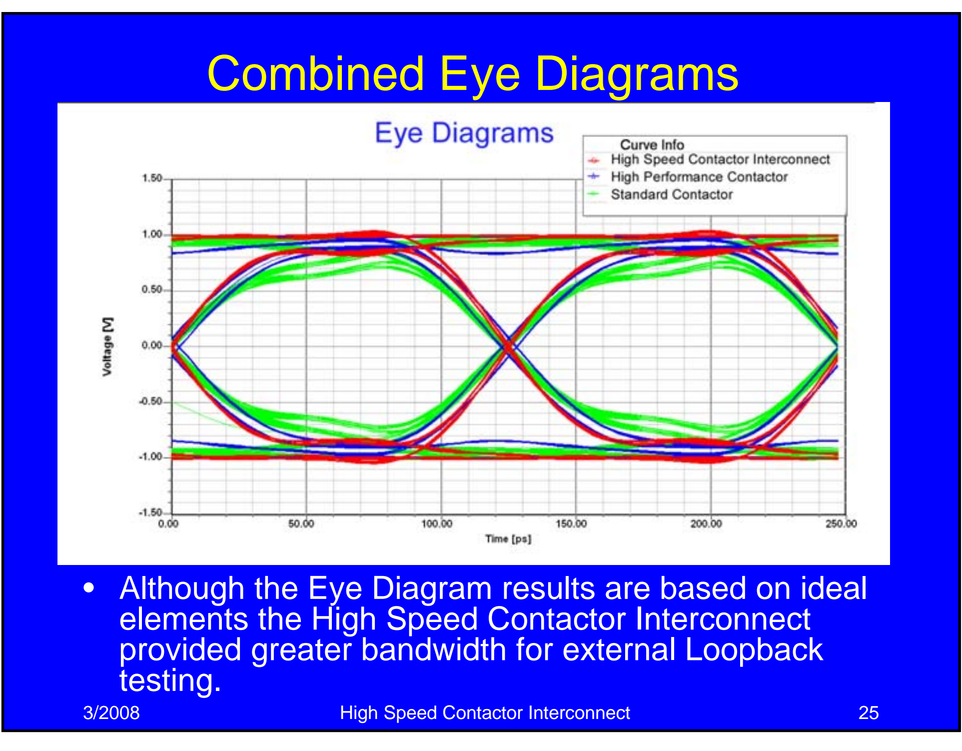


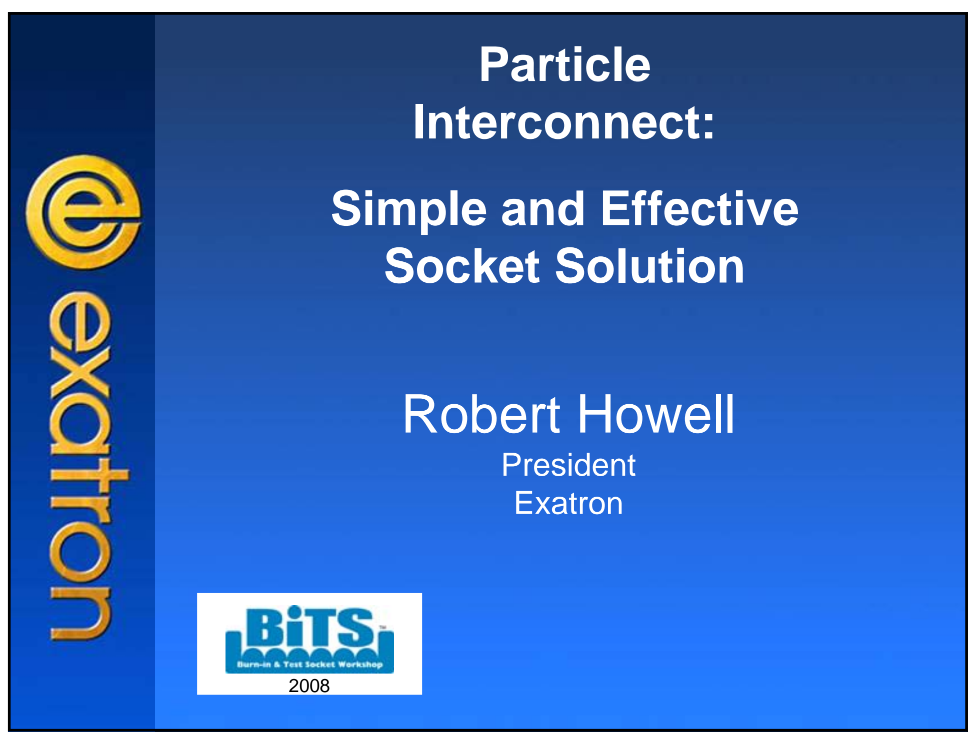
Eye Diagrams
• PRBS Parameters:
– 60pS rise time
– 60pS fall time
– 8Gbps
3/2008
High Speed Contactor Interconnect
24



High Speed Contactor Interconnect Summary

- The High Speed Contactor Interconnect demonstrated greater Bandwidth than a High Performance Contactor with standard loopback traces on the PCB.
- The High Speed Contactor Interconnect maintained both greater working range and higher bandwidth than the High Performance Pogo Pin Contactor.
- The addition of an interconnect in the socket provides greater bandwidth for loop back testing purposes without having to change the entire socket to high performance pogo pins.

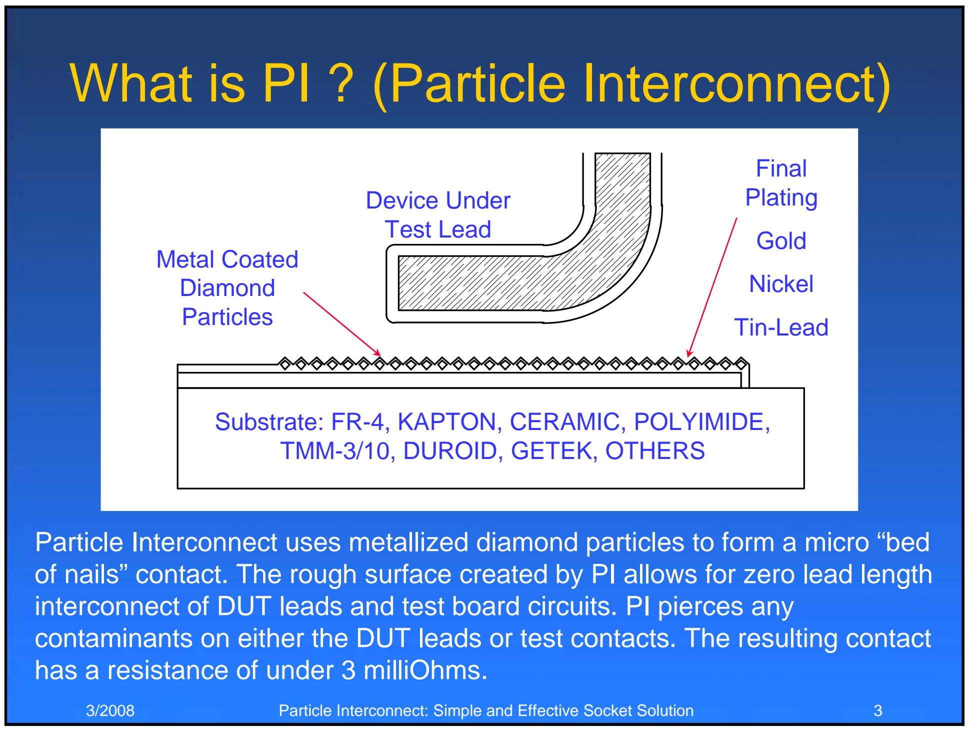
3/2008 High Speed Contactor Interconnect 26



The goal of our presentation will be to convey practical information to allow for in-house self design of "Simple & Effective" test sockets using Particle Interconnect

"PI"

3/2008 Particle Interconnect: Simple and Effective Socket Solution 2


What is PI ? (Particle Interconnect)
Device Under
Test Lead
Final
Plating
Gold
Nickel
Tin-Lead
Metal Coated
Diamond
Particles
Substrate: FR-4, KAPTON, CERAMIC, POLYIMIDE,
TMM-3/10, DUROID, GETEK, OTHERS
Particle Interconnect uses metallized diamond particles to form a micro "bed of nails" contact. The rough surface created by PI allows for zero lead length interconnect of DUT leads and test board circuits. PI pierces any contaminants on either the DUT leads or test contacts. The resulting contact has a resistance of under 3 milliOhms.
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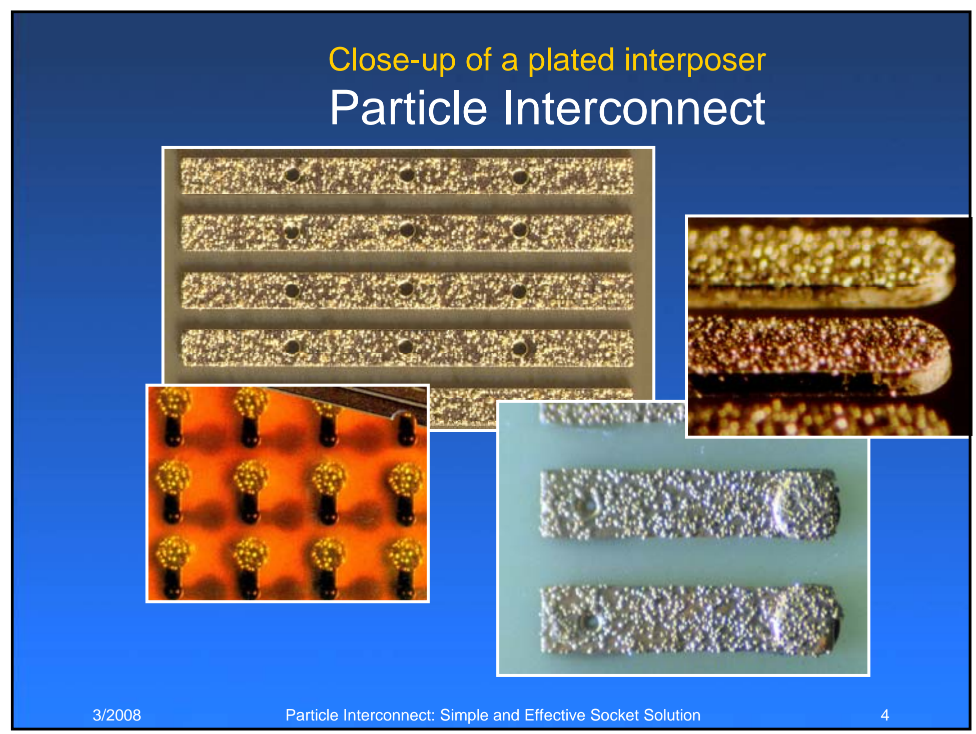
Close-up of a plated interposer
Particle Interconnect
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PI
Electrical Properties

- Contact resistance under 3 milliOhms
- Capacitance approaches zero
- Inductance approaches zero
- Tested to 40 GHz
- Artwork-controlled 50 ohm impedance
- Excellent TDR results

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PI
Mechanical Properties

- Contact pressure 10 to 12 grams / contact
- Contact height typically 0.001”
- -70° C to +200° C temperature range
- Long life:
  over 1,000,000 contacts on rigid material
  over 100,000 contacts on flex material
- No “wiping action” required

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All Particle Interconnect Test Sockets
are
RoHS Compliant
LEAD FREE
Pb
RoHS
COMPLIANT
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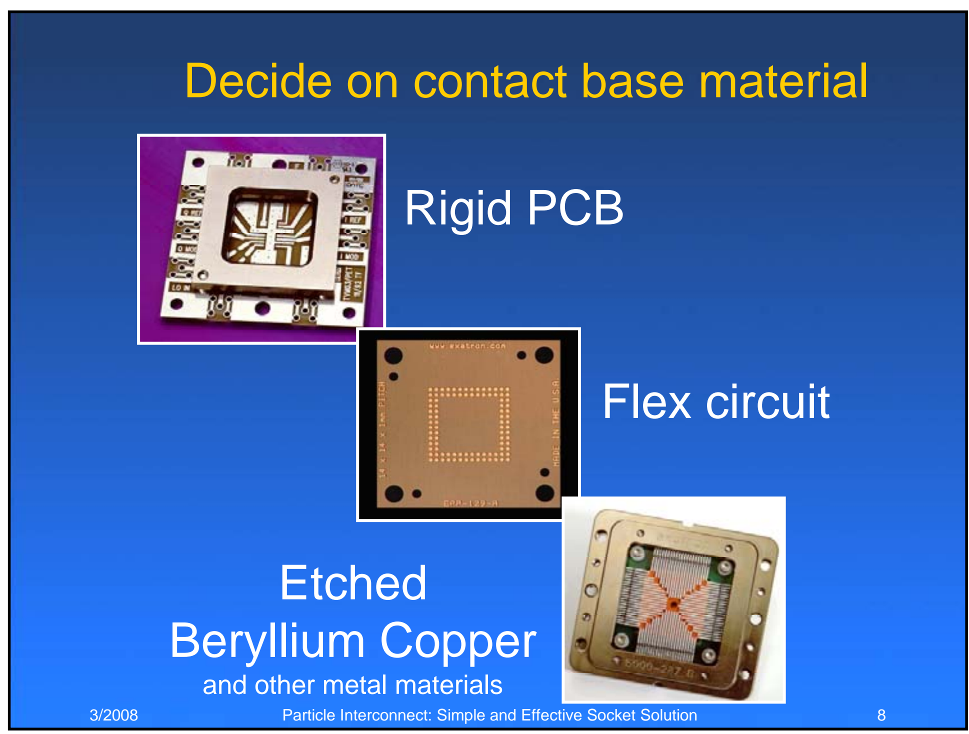
Decide on contact base material
Rigid PCB
Flex circuit
Etched
Beryllium Copper
and other metal materials
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Rigid PCB Applications

- Typically 0.010" or thicker
- Standard FR-4 is the most popular material
- Ceramic, Teflon, G-10 and other special base materials are available
- Works best for devices with flexible leads

SOIC, SSOIC, TSOP, SOT, PLCC, Power Transistors

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Selective Particle Interconnect plating

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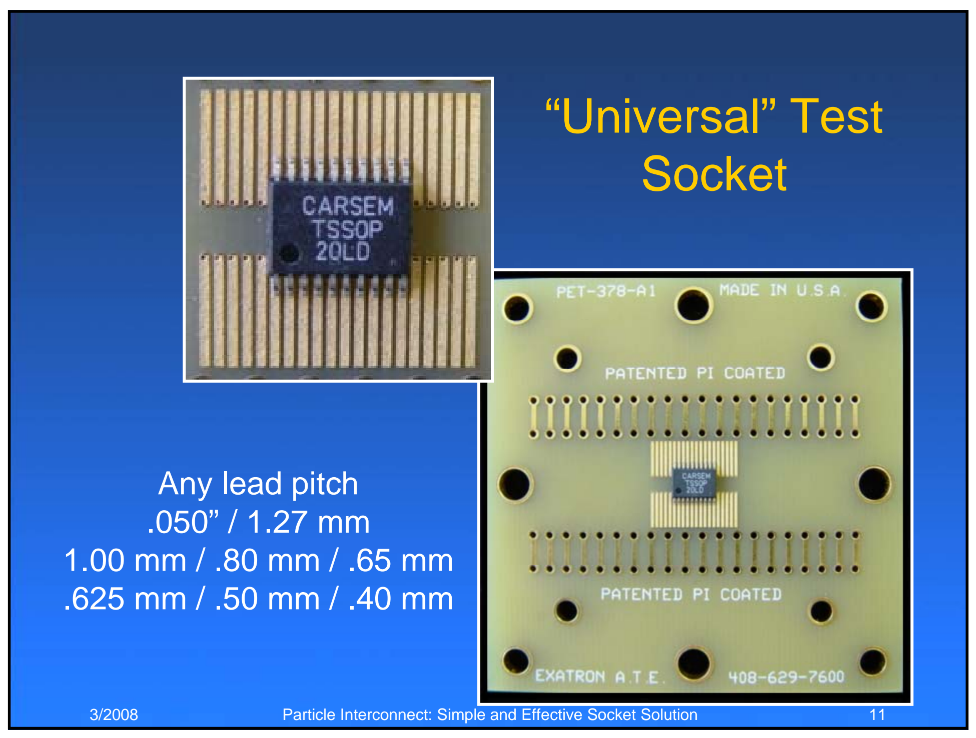
"Universal" Test Socket
CARSEM
TSSOP
20LD
PET-378-A1
MADE IN U.S.A.
PATENTED PI COATED
PATENTED PI COATED
EXATRON A.T.E.
408-629-7600
Any lead pitch
.050" / 1.27 mm
1.00 mm / .80 mm / .65 mm
.625 mm / .50 mm / .40 mm
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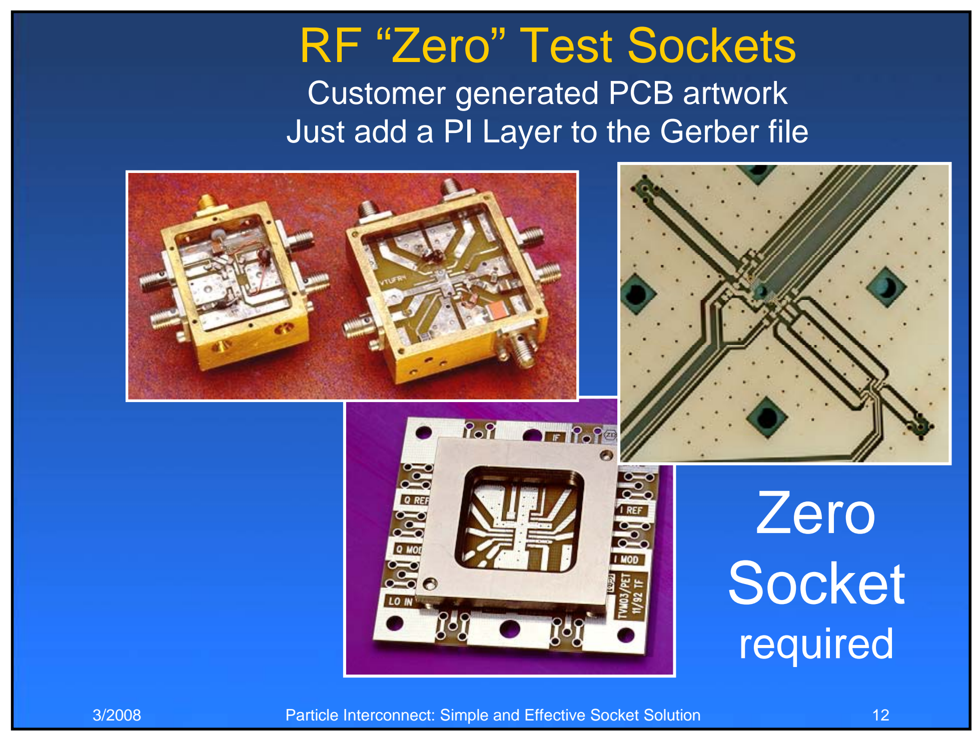
RF "Zero" Test Sockets
Customer generated PCB artwork
Just add a PI Layer to the Gerber file
Zero
Socket
required
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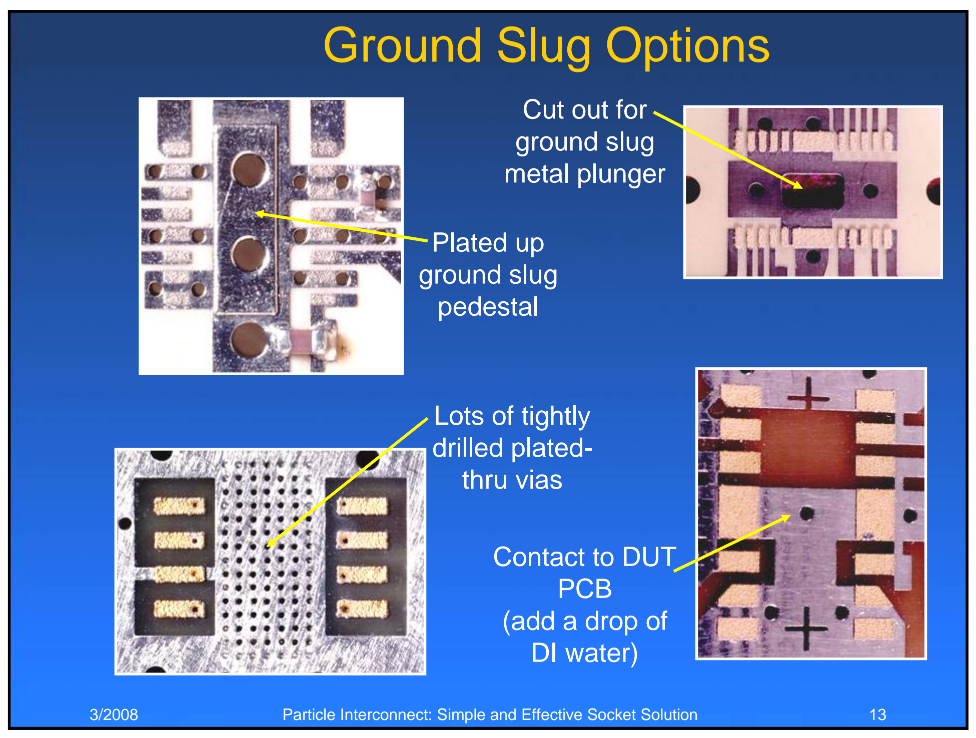
Ground Slug Options
Cut out for ground slug metal plunger
Plated up ground slug pedestal
Lots of tightly drilled plated-thru vias
Contact to DUT PCB (add a drop of DI water)
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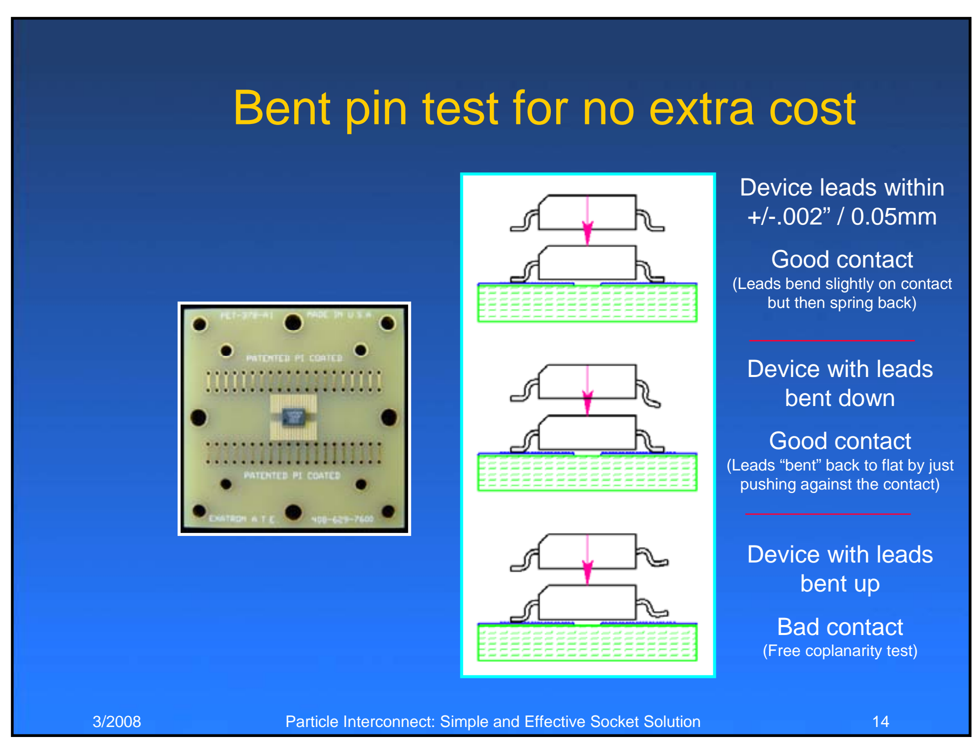
Bent pin test for no extra cost
Device leads within +/-.002" / 0.05mm
Good contact
(Leads bend slightly on contact but then spring back)
Device with leads bent down
Good contact
(Leads "bent" back to flat by just pushing against the contact)
Device with leads bent up
Bad contact
(Free coplanarity test)
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Flex circuit Interposers

- As thin as 0.001” core material
- Standard Kapton is the most popular material
- FR-4 and Teflon materials are available
- Works for all devices*, with some simple help

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* For QFN–MLP-LGA and other devices with no leads, some compliance will need to be added to or built-in to the flexible interposer

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Which materials?

Teflon: Best electrical properties (best for RF / 40 GHz)
Most flexible
Shortest mechanical life

Kapton: Good electrical properties (includes most RF)
Most popular to date
100K contacts minimum mechanical life

FR-4: Basic electrical properties
Allows for best mechanical compliance
100K contacts minimum mechanical life

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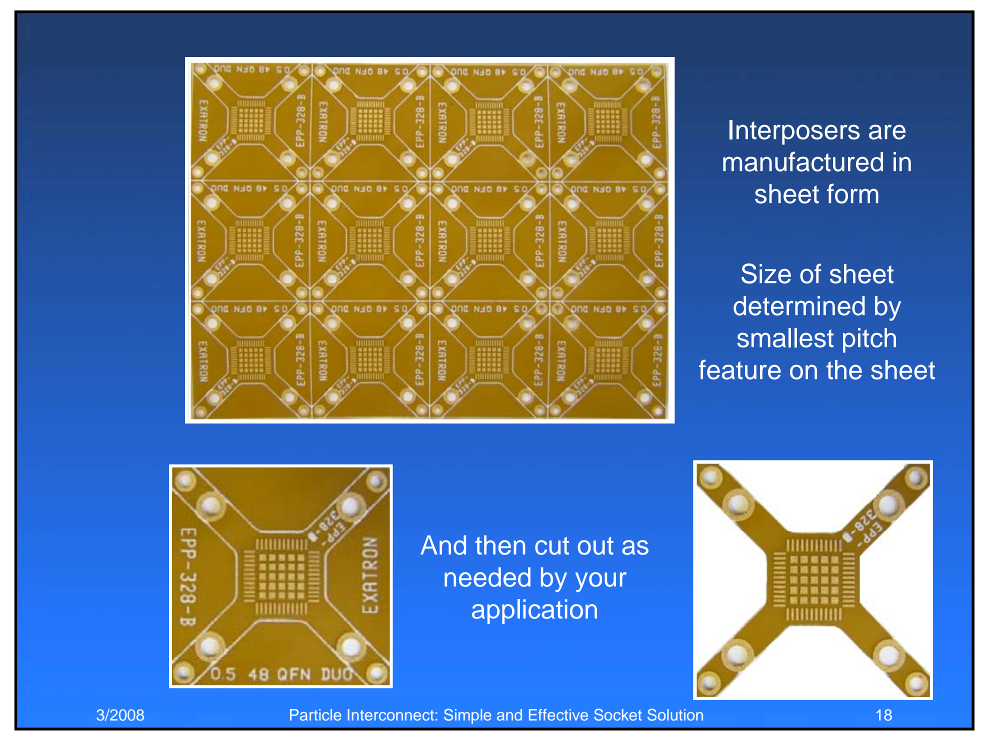

Kapton Interposers
Simple 2 sided Gerber File
Easily adapted to ANY existing socket footprint
Multiple socket patterns on one sheet
Pitch to 0.3mm
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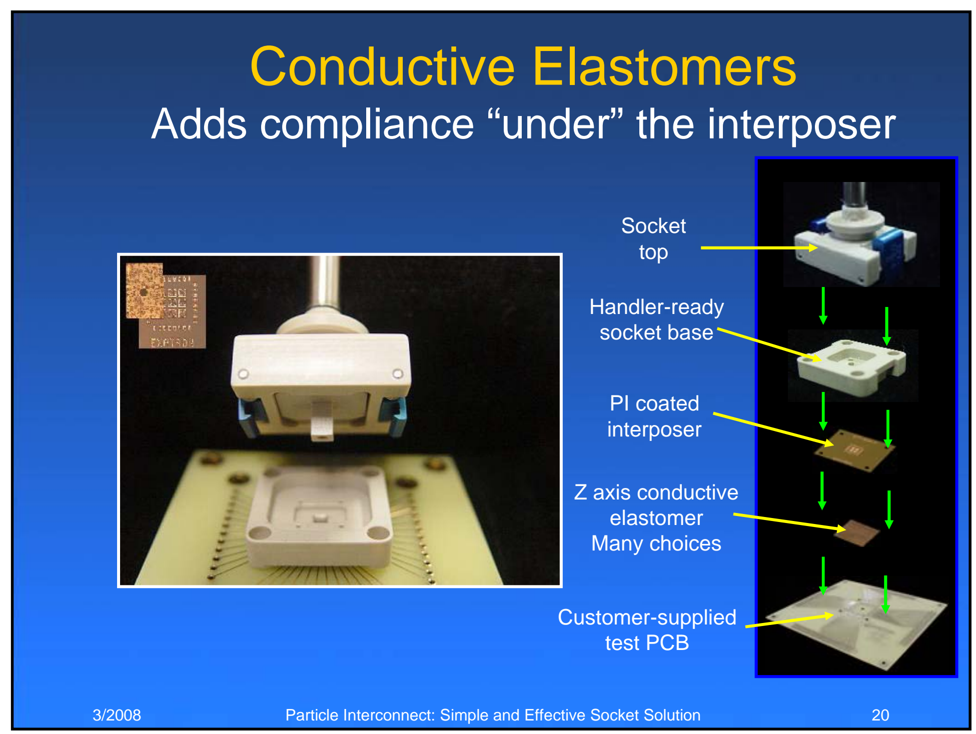
Conductive Elastomers
Adds compliance "under" the interposer
Socket
top
Handler-ready
socket base
PI coated
interposer
Z axis conductive
elastomer
Many choices
Customer-supplied
test PCB
3/2008
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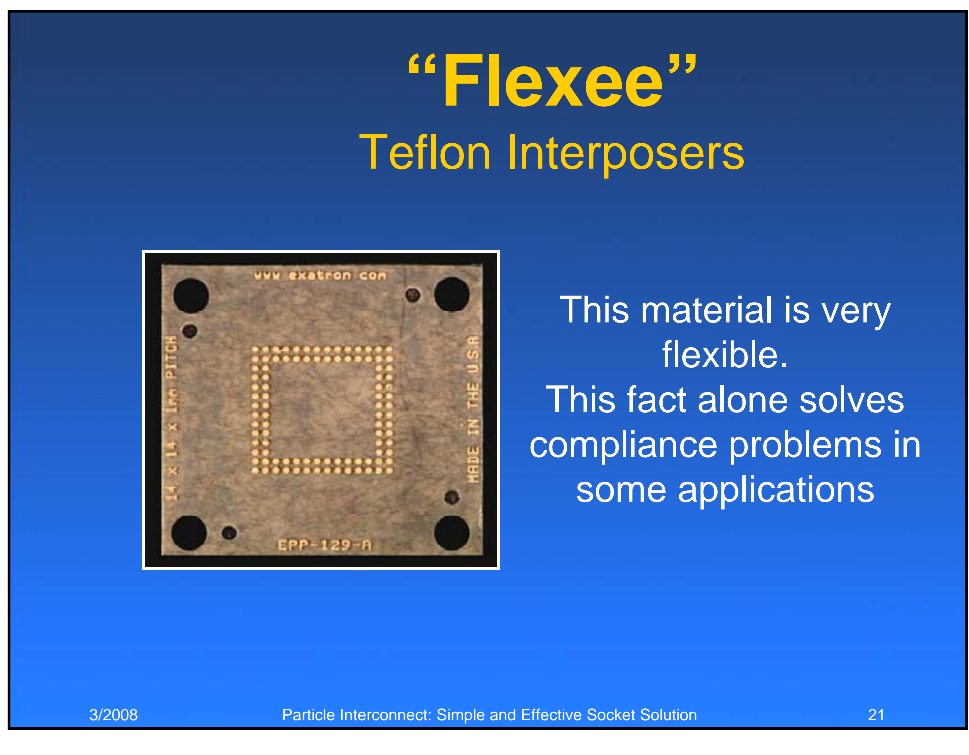
"Flexee"
Teflon Interposers
www exatron com
14 x 14 x 1mm PITCH
MADE IN THE U.S.A
EPP-129-A
This material is very flexible.
This fact alone solves compliance problems in some applications
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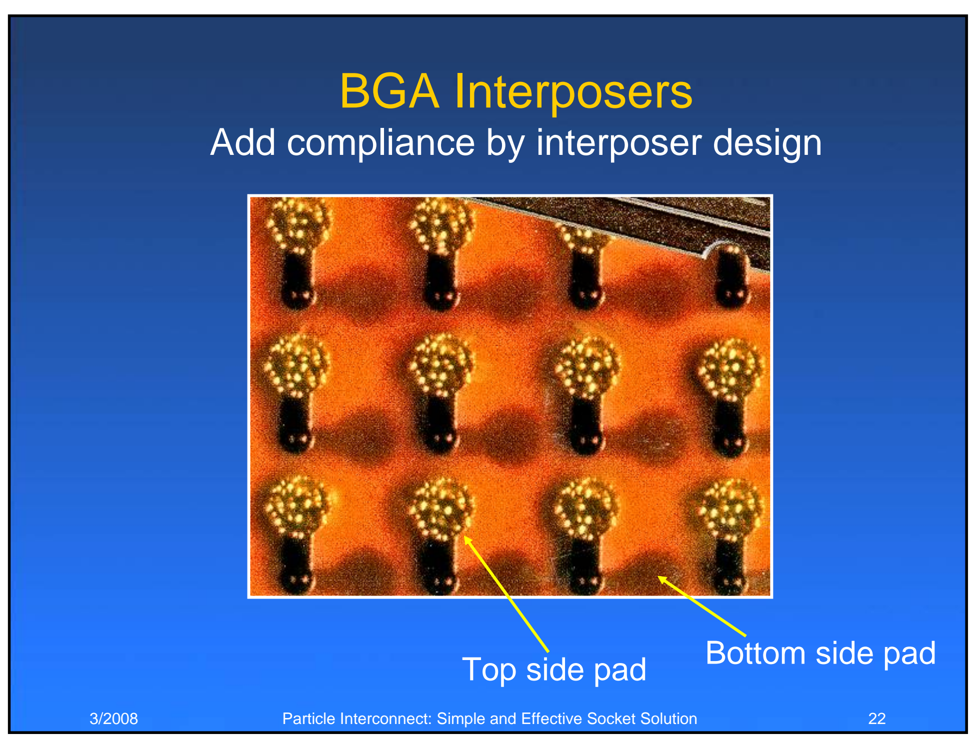
BGA Interposers
Add compliance by interposer design
Top side pad
Bottom side pad
3/2008
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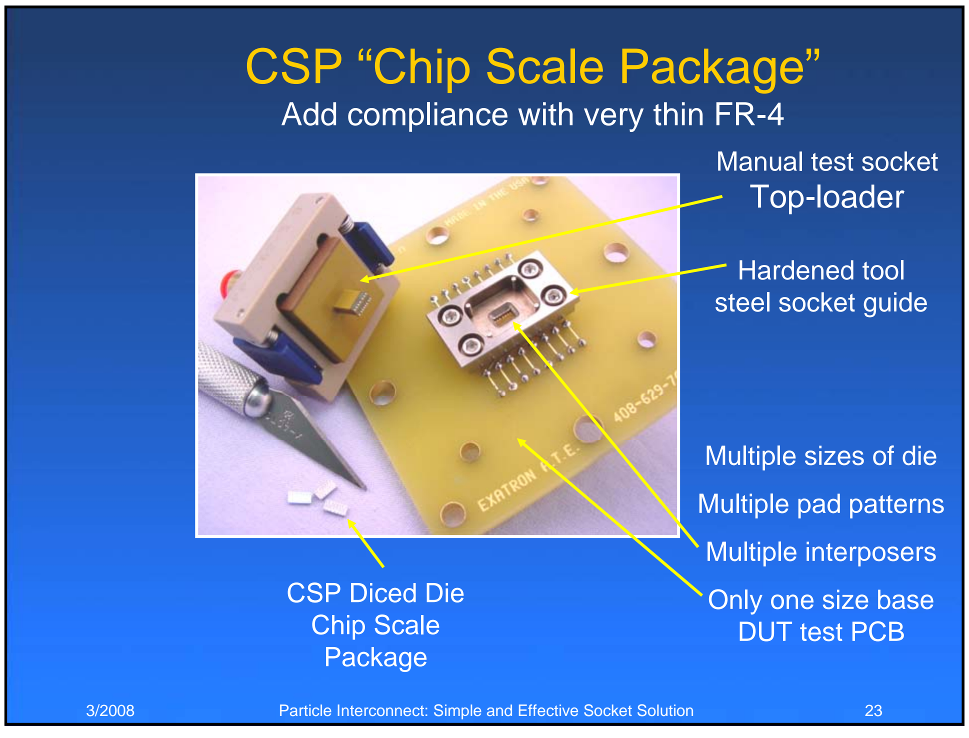

CSP "Chip Scale Package"
Add compliance with very thin FR-4
Manual test socket
Top-loader
Hardened tool steel socket guide
Multiple sizes of die
Multiple pad patterns
Multiple interposers
Only one size base DUT test PCB
CSP Diced Die Chip Scale Package
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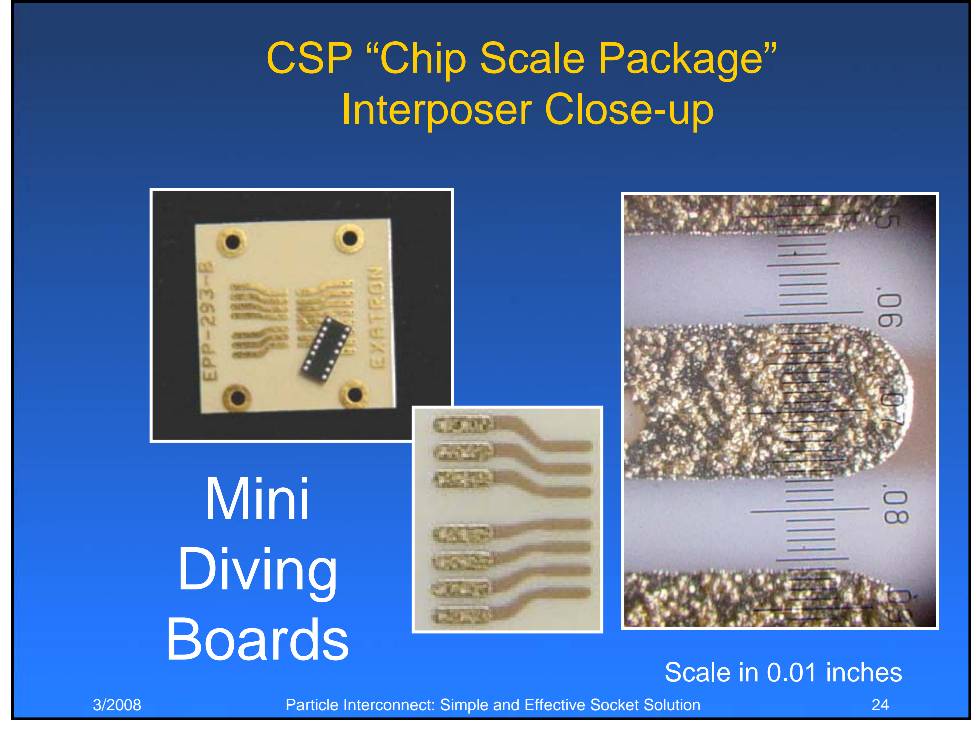

CSP "Chip Scale Package"
Interposer Close-up
Mini Diving Boards
Scale in 0.01 inches
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DUO-Compliant Interposers

Adds compliance “within” the interposer

- Allows up to 0.004”/0.1mm of compliance
- Brings otherwise ruined DUT test boards back to life!
- There are additional ways to add compliance “in the works”

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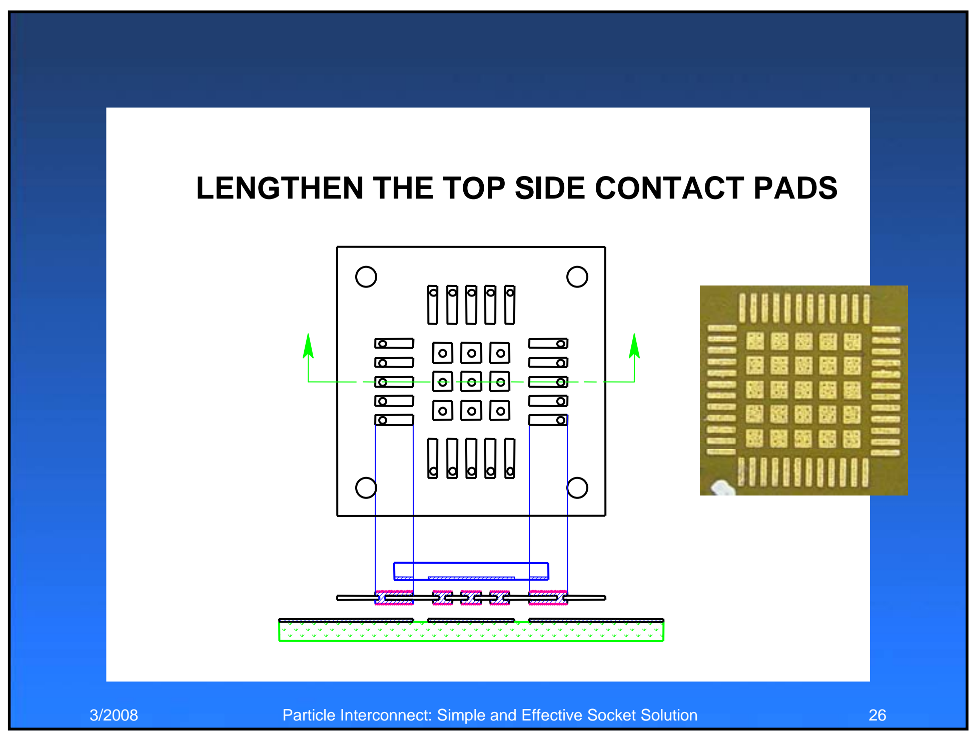

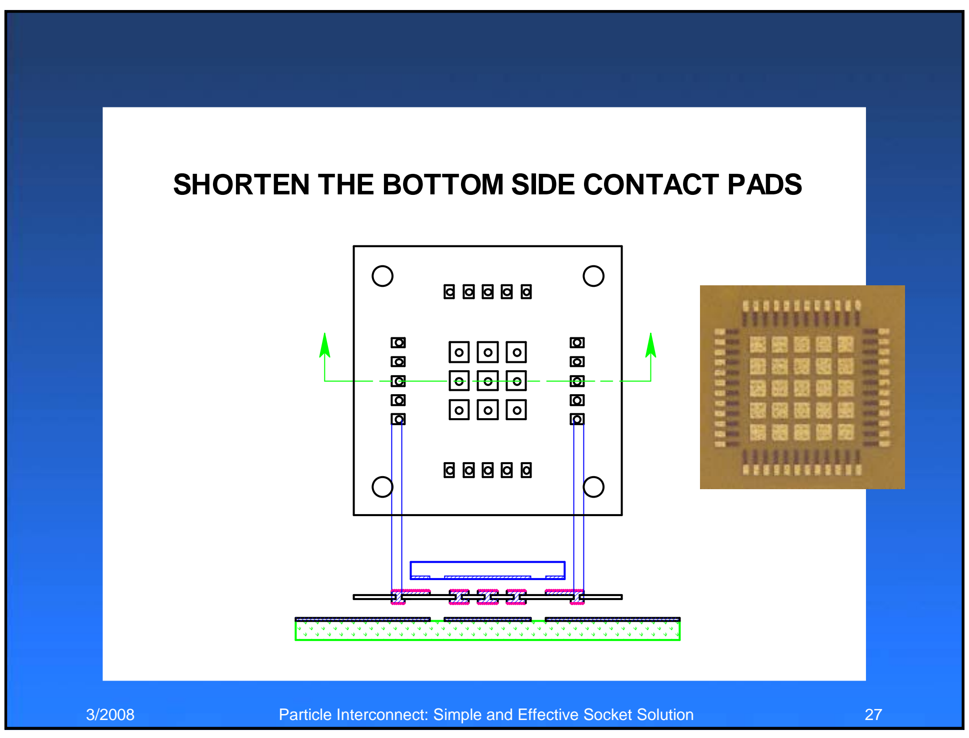

SHORTEN THE BOTTOM SIDE CONTACT PADS
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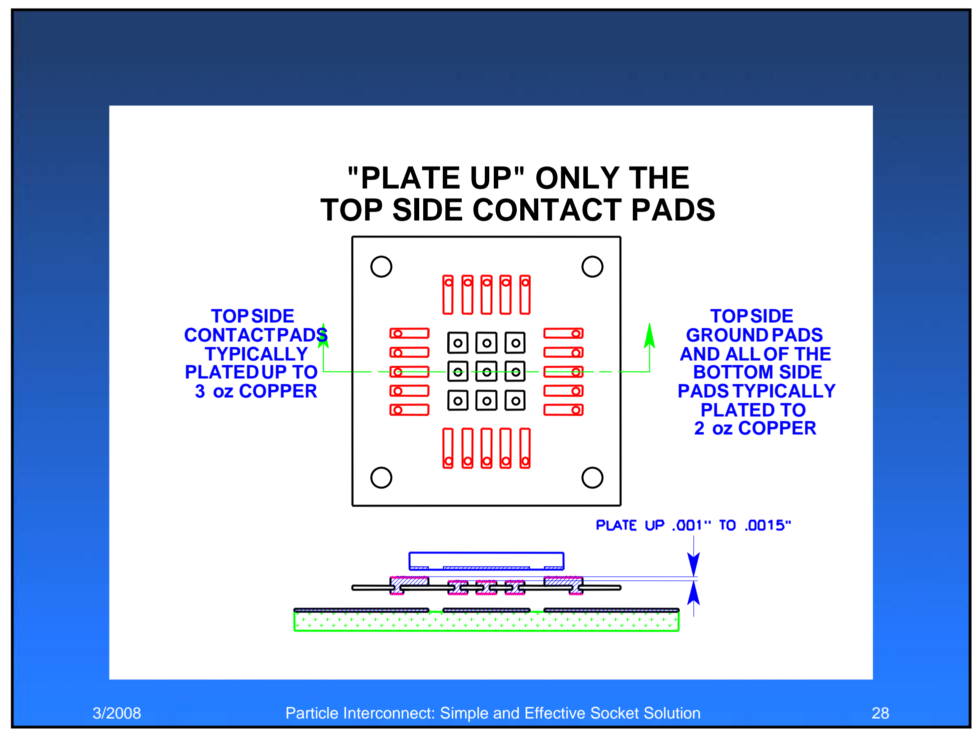

"PLATE UP" ONLY THE
TOP SIDE CONTACT PADS
TOP SIDE
CONTACT PADS
TYPICALLY
PLATED UP TO
3 oz COPPER
TOP SIDE
GROUND PADS
AND ALL OF THE
BOTTOM SIDE
PADS TYPICALLY
PLATED TO
2 oz COPPER
PLATE UP .001" TO .0015"
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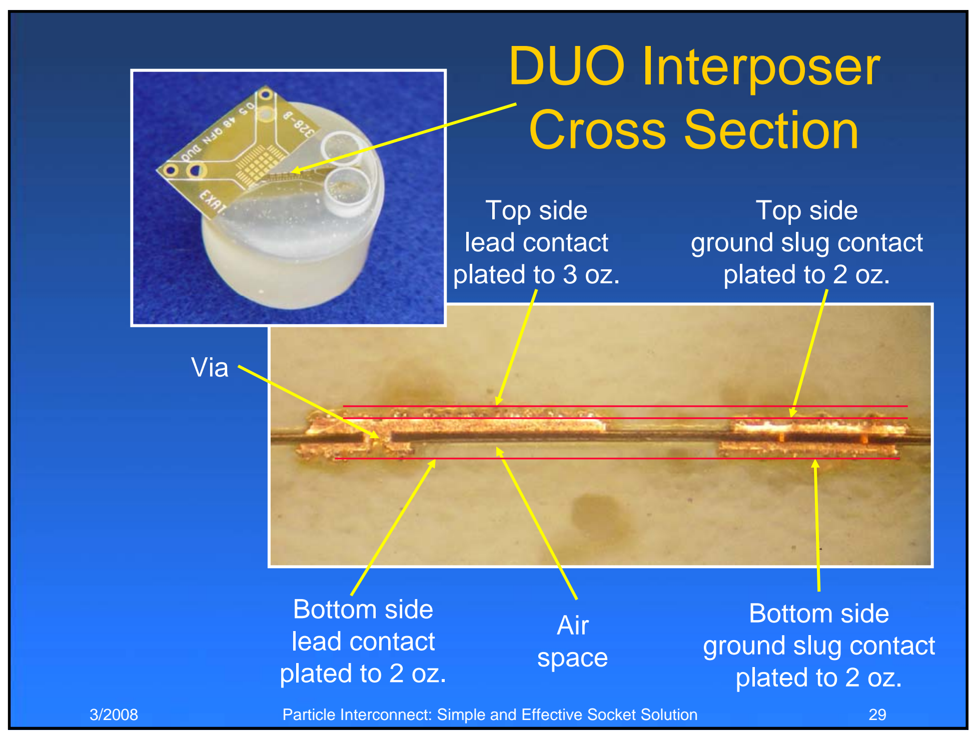

DUO Interposer
Cross Section
Top side
lead contact
plated to 3 oz.
Top side
ground slug contact
plated to 2 oz.
Via
Bottom side
lead contact
plated to 2 oz.
Air
space
Bottom side
ground slug contact
plated to 2 oz.
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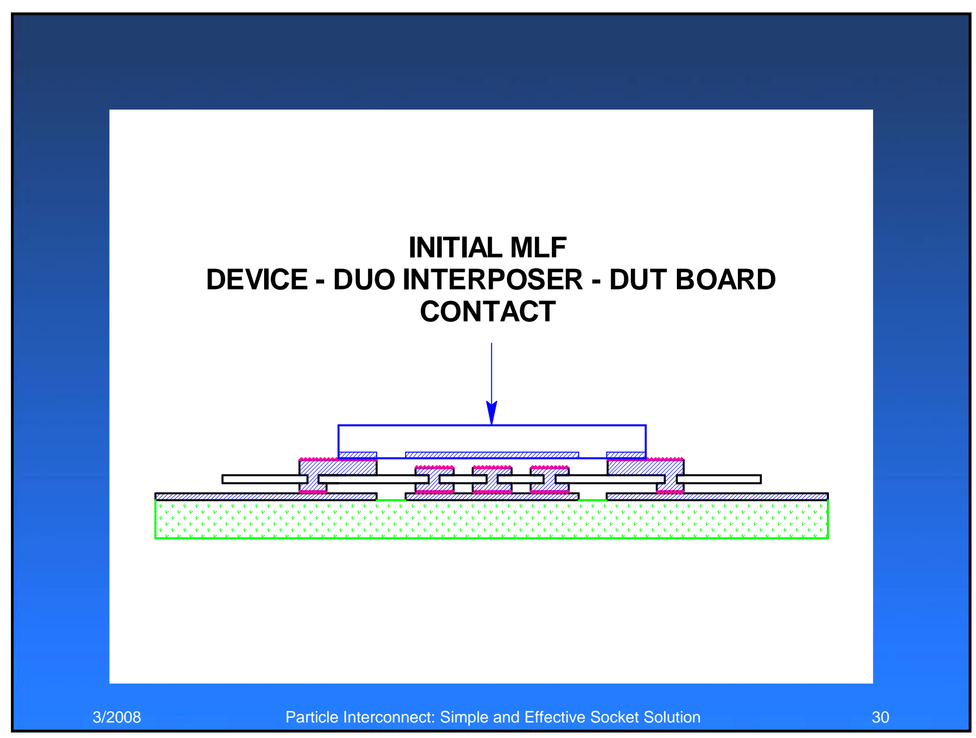

INITIAL MLF
DEVICE - DUO INTERPOSER - DUT BOARD
CONTACT
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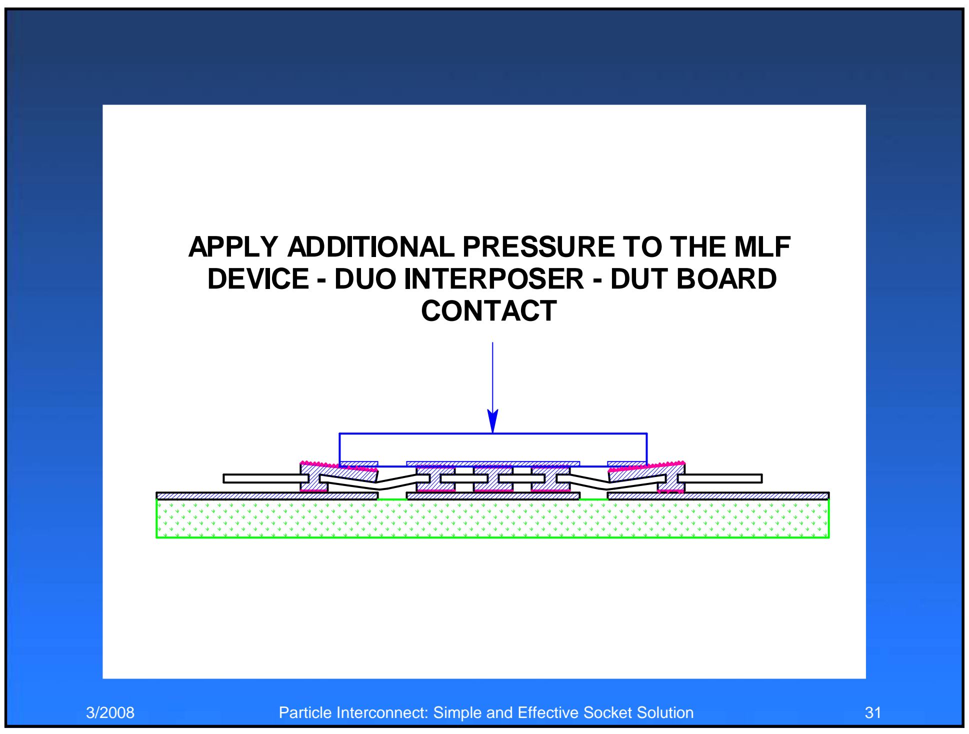
APPLY ADDITIONAL PRESSURE TO THE MLF DEVICE - DUO INTERPOSER - DUT BOARD CONTACT
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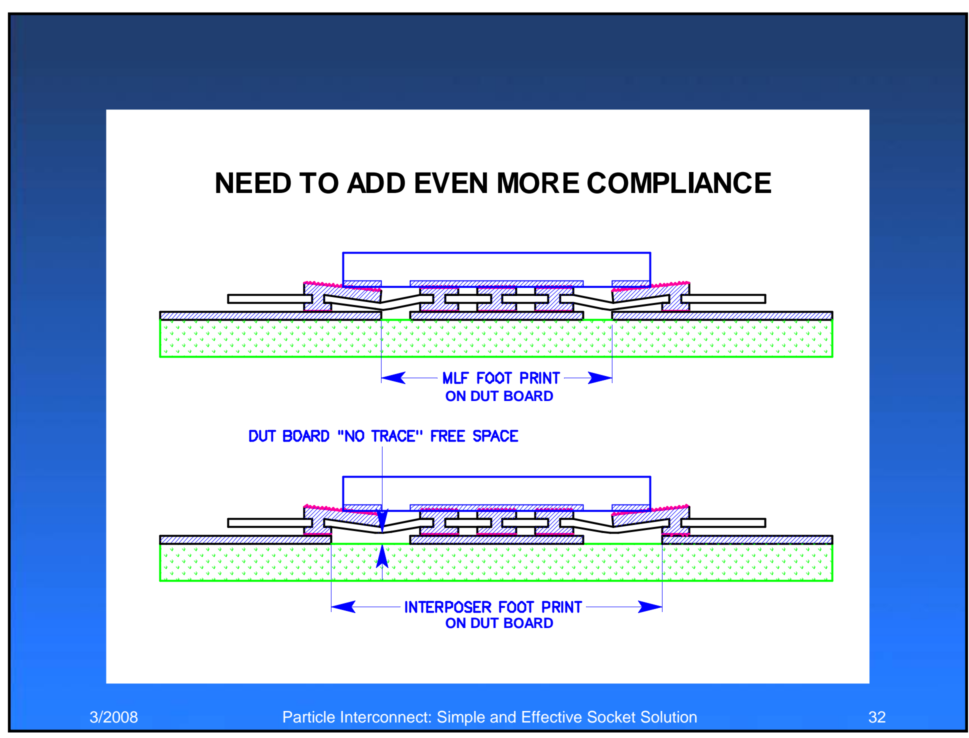
NEED TO ADD EVEN MORE COMPLIANCE
MLF FOOT PRINT
ON DUT BOARD
DUT BOARD "NO TRACE" FREE SPACE
INTERPOSER FOOT PRINT
ON DUT BOARD
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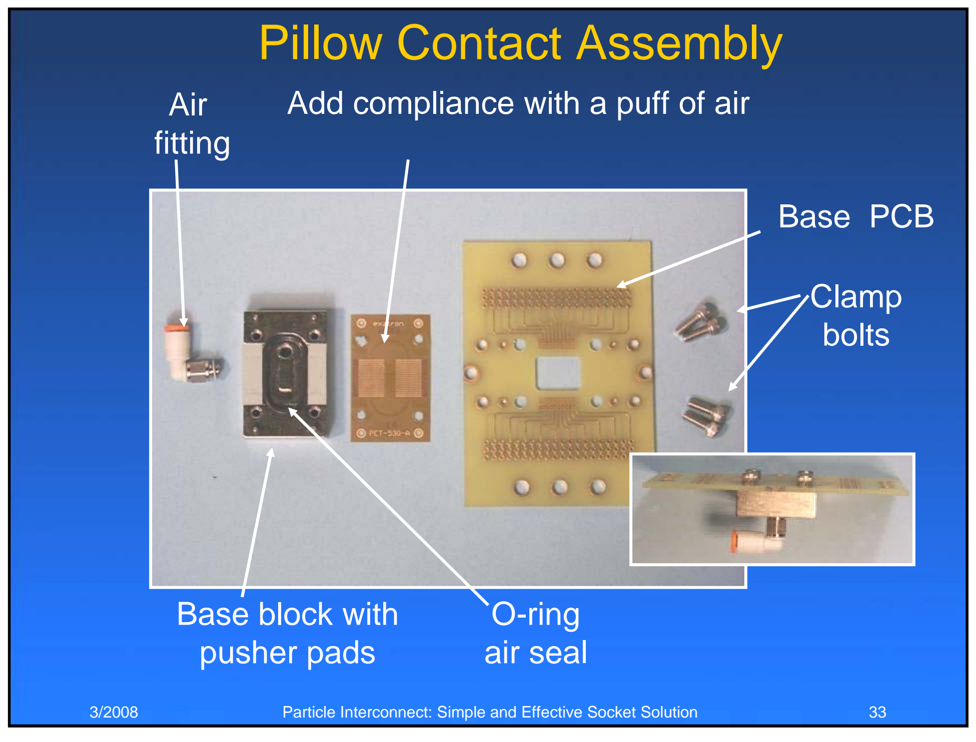
Pillow Contact Assembly
Air fitting
Add compliance with a puff of air
Base PCB
Clamp bolts
Base block with pusher pads
O-ring air seal
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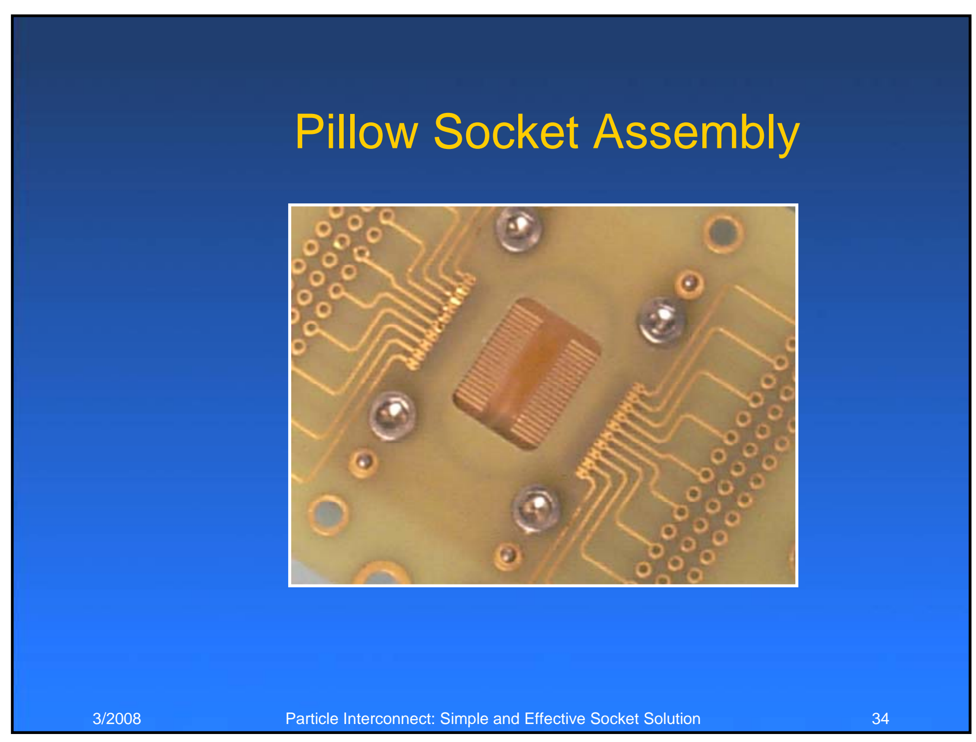
Pillow Socket Assembly
3/2008
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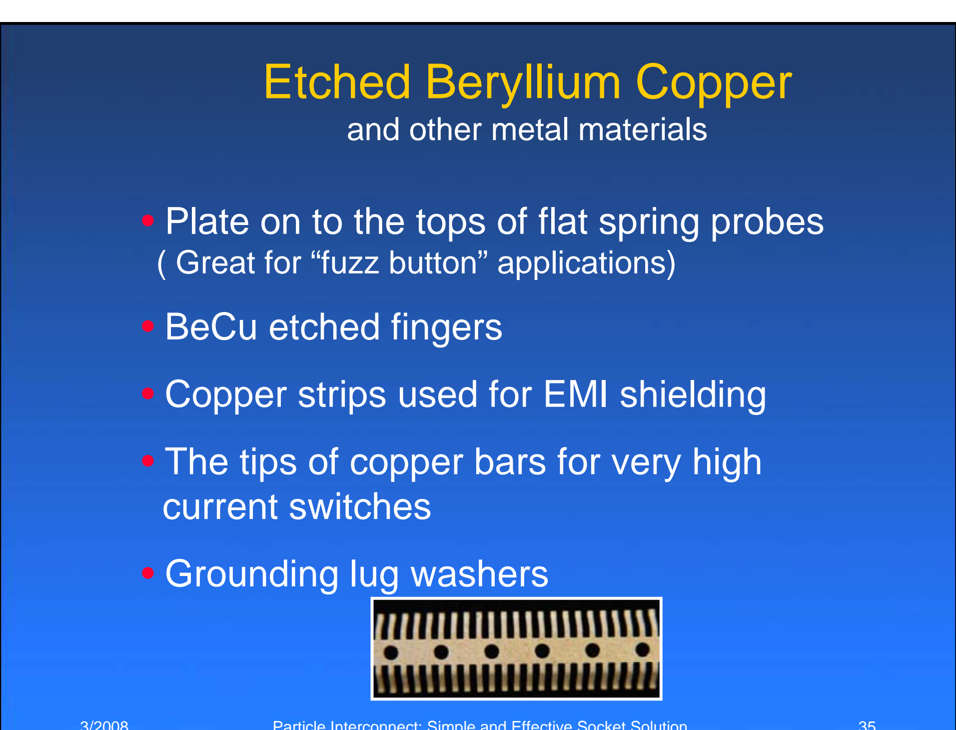
Etched Beryllium Copper
and other metal materials
Plate on to the tops of flat spring probes
(Great for "fuzz button" applications)
BeCu etched fingers
Copper strips used for EMI shielding
The tips of copper bars for very high current switches
Grounding lug washers
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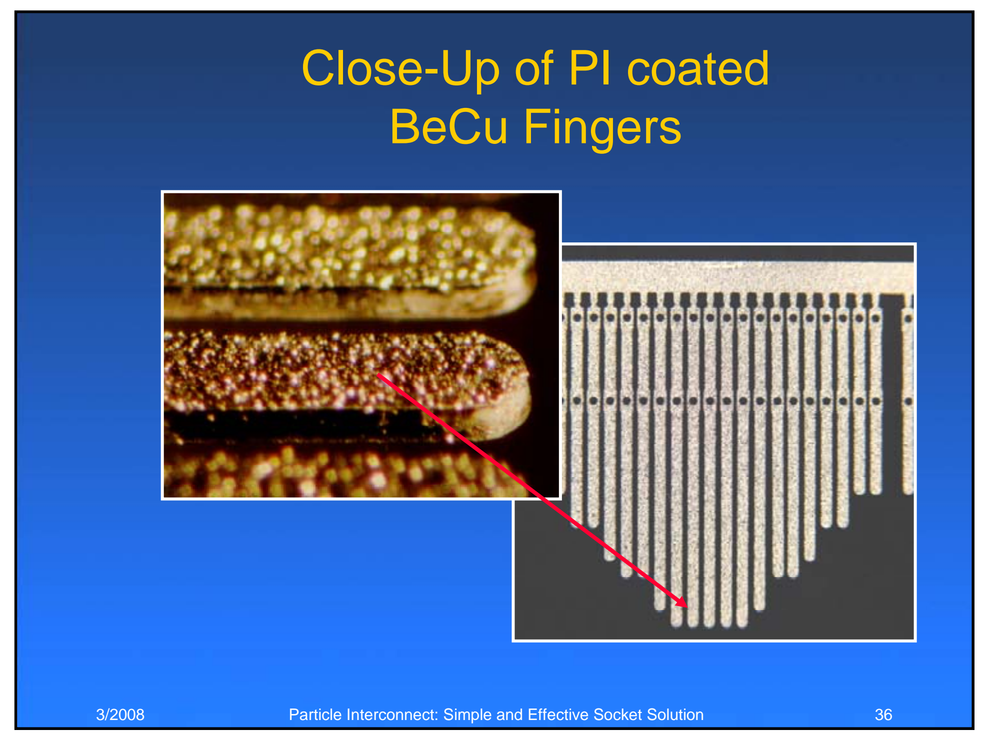
Close-Up of PI coated
BeCu Fingers
3/2008
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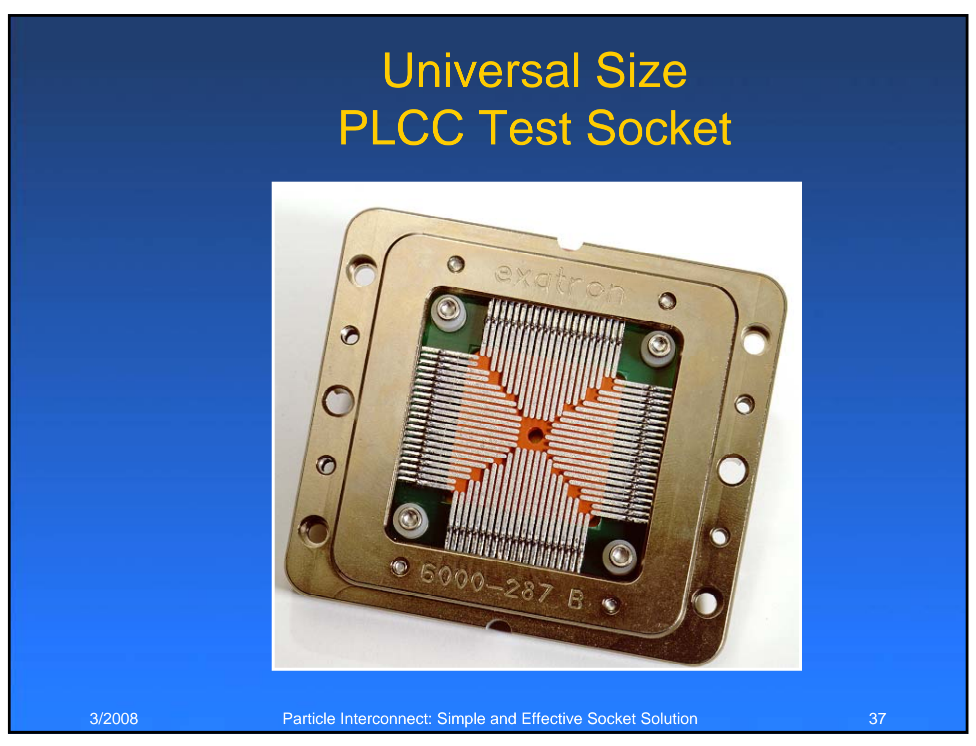
Universal Size
PLCC Test Socket
exatron
6000-287 B
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Thank You
3/2008
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